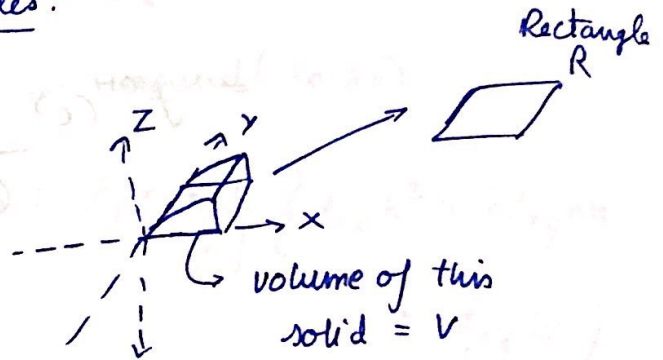


Integrating functions on two variables:

$$V = \iint_R f(x,y) dx dy$$



Here also there is Darboux Sum & Riemann Sum, but everything in two dimensions.

norm of a partition P:

$$\|P\| = \max \left\{ (x_{i+1} - x), (y_{j+1} - y_j) \mid \begin{matrix} i = 0 \dots m-1 \\ j = 0 \dots n-1 \end{matrix} \right\}$$

\*

$$f_{\min} \cdot A \leq L(f, P) \leq R(f, P) \leq U(f, P) \leq f_{\max} \cdot A$$

$$A = (b-d)(a-c)$$

$$R = [a, b] \times [c, d]$$

Theorem (Riemann condition):

Let  $f: R \rightarrow \mathbb{R}$  be a bounded fn. Then  $f$  is integrable if & only if for every  $\epsilon > 0$  there is a partition  $P_\epsilon$  of  $R$  such that:

$$|U(f, P_\epsilon) - L(f, P_\epsilon)| < \epsilon$$

\* Regular partitions: equally spaced along each axis.

to check integrability of a fn, it is enough to use regular partitions.

\* Domain additivity property: Integral over a rectangle  $R$  = sum of areas over sub-rectangles which make up  $R$ .

\*

$$|\iint_R f| \leq \iint_R |f|$$

Fubini Theorem & the iterated Integrals:

let  $R = [a, b] \times [c, d]$  and  $f: R \rightarrow \mathbb{R}$  be integrable. Let  $I$  denote the integral of  $f$  on  $R$ .

1. if for each  $x \in [a, b]$ , the Riemann integral  $\int_c^d f(x, y) dy$  exists, then the iterated integral  $\int_a^b \int_c^d f(x, y) dy dx$  exists & is equal to  $I$ .

2. if for each  $y \in [c, d]$ , the Riemann integral  $\int_a^b f(x, y) dx$  exists, then the iterated integral  $\int_c^d \int_a^b f(x, y) dx dy$  exists & is equal to  $I$ .

$\therefore$  if  $f$  is integrable on  $R$   
& &

both it.  $\int$  exists

ONLY THEN

$$I = I_1 = I_2$$





\*\*\* :

★ Both iterated integrals may exist but the function may not be integrable.

eg.  $R = [0, 1] \times [0, 1]$

$$f(x, y) = \begin{cases} \frac{xy(x^2 - y^2)}{(x^2 + y^2)^3}, & (x, y) \neq (0, 0) \\ 0, & (x, y) = (0, 0) \end{cases}$$

- ★ The function  $f$  may be double integrable, but one of the iterated integrals may not exist.
- ★ if  $f$  is a cont. fn. on its domain, then for sure 100% both iterated integrals will exist & the fn. will be double integrable.
- ★ if  $f$  is bounded & monotone in both  $x, y$  then  $f$  is double integrable.
- ★ if a fn. is bounded & continuous on  $R$  except possibly & finitely many points in  $R$ , then  $f$  is double integrable.

alternate version:

if  $f$  is bounded + cont. except possibly along a finite no. of graphs of continuous fns, then  $f$  is integrable on  $R$ .

fancy way:  $f$  is integrable if pts. of discontinuity of  $f$  is a set of "content zero".

BUT

There are fns. who have discont. which isn't content zero but they are still integrable!

\* when we have fns. defined over areas which aren't rectangles, we make a rectangle containing that fn. & then do  $\iint f dx dy$ .

→ choice of rectangle does not matter as only 0 is getting added outside.

\* The boundary of area  $D \in \mathbb{R}^2$  is given by  $\partial D$

$\partial D$  is of content zero  $\rightarrow f$  is int

$f$  is int  $\nrightarrow \partial D$  is of content zero.



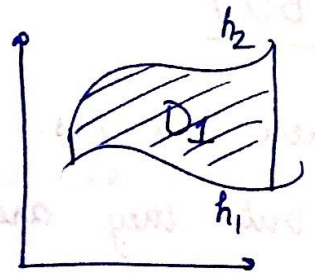
Elementary Region: Type 1:

Let  $h_1, h_2 : [a, b] \rightarrow \mathbb{R}$  be two cont. fns  
such that  $h_1(x) \leq h_2(x) \quad \forall x \in [a, b]$

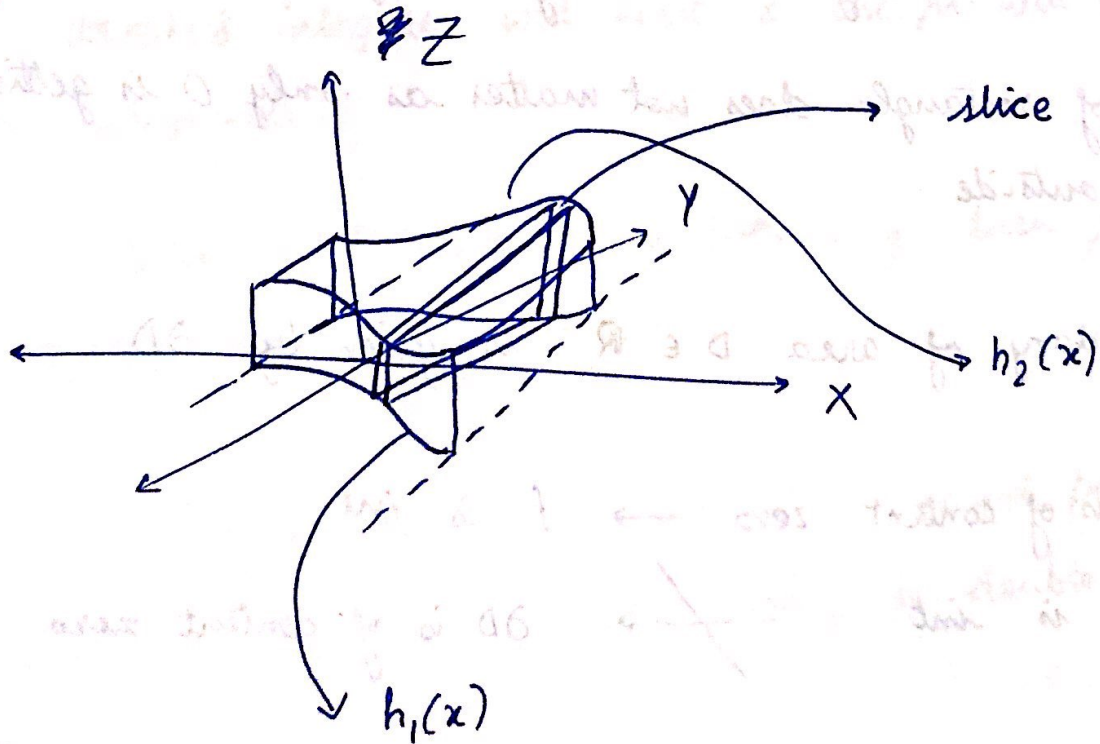
Consider the region  $D_1$ .

$$D_1 = \left\{ (x, y) \mid a \leq x \leq b \quad \text{and} \quad h_1(x) \leq y \leq h_2(x) \right\}$$

$D_1 \rightarrow$  Type 1 region



$\therefore$  Double integrals on this region:



$$\text{volume} = \int \text{slice } dx$$

$$\text{slice} = \int f \, dy$$



→ limits of slice integral?

→  $h_1(x)$  &  $h_2(x)$  at that  $x$

$$\therefore \text{slice} = \int_{h_1(x)}^{h_2(x)} f(x, y) \, dy$$

→ limits of volume?

$x$  coordinate boundaries of  $D_1$

$$\text{volume} = \int_a^b \text{slice}(x) \, dx$$

$$\therefore V = \int_a^b \int_{h_1(x)}^{h_2(x)} f(x, y) \, dy \, dx$$



### Elementary region : Type 2:

Basically, everything interchanges axes.  
now, region is sandwiched b/w two curves of  $y$ .  
and we take slices along the other axis.

$$V = \int_c^d \int_{k_1(y)}^{k_2(y)} f(x,y) dx dy$$

$c, d \rightarrow y$  boundaries of fn.

$k_1(y), k_2(y) \rightarrow$  cont. curves bounding the region.

eg. Let  $D = \{ (x,y) \mid x^2 + y^2 \leq 1, x \geq 0, y \geq 0 \}$   $f(x,y) = \sqrt{1-y^2}$

calculate  $\iint_D \sqrt{1-y^2} dx dy$

M-I:

Type-1 region

$$0 \leq x \leq 1$$

$$0 \leq y \leq \sqrt{1-x^2}$$

$$\therefore V = \int_0^1 \int_0^{\sqrt{1-x^2}} \sqrt{1-y^2} dy dx$$

↳ annoying integral.

let's try M-II:

Type - 2 region

$$0 \leq y \leq 1$$

$$0 \leq x \leq \sqrt{1-y^2}$$

$$V = \int_0^1 \int_0^{\sqrt{1-y^2}} \sqrt{1-y^2} dx dy$$

$$= \int_0^1 |x \sqrt{1-y^2}|_0^{\sqrt{1-y^2}} dy$$

$$= \int_0^1 (1-y^2) dy = \frac{2}{3}$$

... easy!

\* Type 1 & 2 unions  $\rightarrow$  Type 3 (star shaped or annulus)



Polar coordinates:

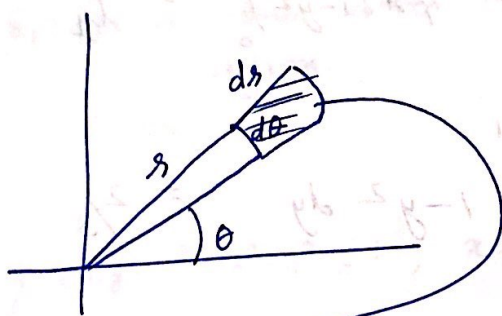
$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$D = \{(x, y) \in \mathbb{R}^2 \mid x^2 + y^2 \leq a\}$$

$$D^* = \{(r, \theta) \mid r \in [0, a], \theta \in [0, 2\pi]\}$$

Rectangles in polar coordinates?



$$A = \frac{1}{2} [(r+dr)^2 d\theta - r^2 d\theta]$$

$$\sim r dr d\theta$$

$$\begin{aligned} & \therefore \iint_D f(x,y) \, dA \\ & = \iint_D f(x,y) \, dx \, dy = \iint_{D^*} f(r \cos \theta, r \sin \theta) \, r \, dr \, d\theta \end{aligned}$$

Eg:  $\iint_D f(x,y) \, dx \, dy$  ;  $f(x,y) = x^2 + y^2$

$$D = \{ (x,y) \mid x^2 + y^2 \leq 1 \}$$

transform to polar coords.

$$D^* = \{ (r, \theta) \mid r \in [0, 1], \theta \in [0, 2\pi] \}$$

$$f = x^2 + y^2 = r^2$$

$$\therefore V = \int_0^{2\pi} \int_0^1 r^2 \cdot r \, dr \, d\theta = \int_0^{2\pi} \left. \frac{r^4}{4} \right|_0^1 d\theta$$

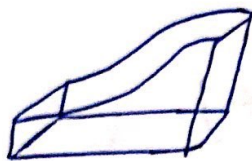
$$= \int_0^{2\pi} \frac{1}{4} \, d\theta = \frac{\pi}{2}$$



Mean value theorem for double integrals:

if  $D$  is an elementary region in  $\mathbb{R}^2$  and  $f: D \rightarrow \mathbb{R}$  is continuous, there exists  $(x_0, y_0)$  in  $D$  such that:

$$f(x_0, y_0) \times A(D) = \iint_D f(x, y) dx dy$$



← his volume is equal to his volume →



area =  $A(D)$

\* now we going to do triple integration.  
visualising bt ko skta hai.

→ Riemann sum again:  $S(f, P_n, t) = \sum_i \sum_j \sum_k f(t_{ijk}) \Delta B_{ijk}$

$\downarrow$   $\downarrow$   
 $f(t_{ij})$       volume of element

if  $S(f, P_n, t)$  converges to  $S$ , then  $f$  is integrable.

$$\iiint_B f dV$$

\* Integrating over bound regions  $B$  in  $\mathbb{R}^3$ .

if  $f: B \subset \mathbb{R}^3 \rightarrow \mathbb{R}$  is bounded and continuous, except at a finite union of graphs of cont. fns of the form:

$$\begin{aligned} z &= f_1(x, y) \\ z &= f_2(y, z) \\ y &= f_3(x, z) \end{aligned}$$

then it is integrable.

if  $\iiint_{B^*} f^*$  exists then it is equal to  $\iiint_B f \rightarrow$  original fn.  
 $B^*$   $\downarrow$   $f^* + \text{extra zeroes}$   
 Rectangular cuboid  $\downarrow$  edge volume

\* Fubini's theorem:

1. if  $f$  is integrable, any iterated integral that exists HAS TO BE EQUAL TO THE TRIPLE INTEGRAL!

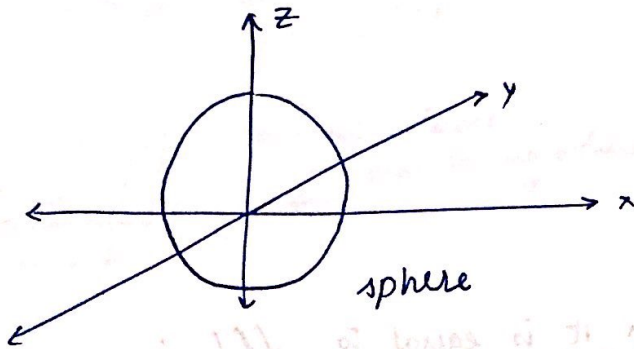
$$\iiint_B f \, dV = \int_{x_1}^{x_2} \int_{y_1}^{y_2} \int_{z_1}^{z_2} f \, dz \, dy \, dx$$

$\hookrightarrow$  if he exists

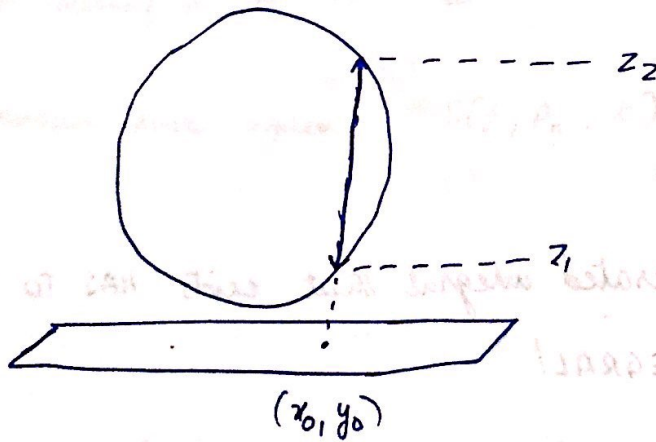


\* if  $f$  is cont. on  $B$ , then  $f$  is integrable on  $B$  and all iterated integrals exist & their values are equal to  $B$ .

\*



First, lets make a line segment at every  $(x, y)$  in the domain of this  $\Omega$ .

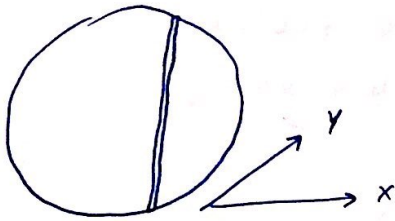


$$I = \int_{z_1}^{z_2} dz$$

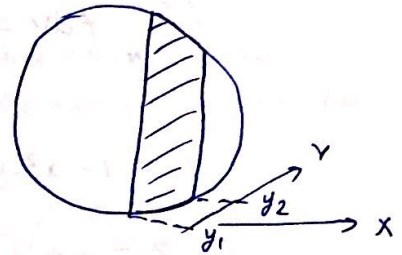
$z_1, z_2$  are functions of  $(x, y)$

now lets make an area segment

$$A = \int_{y_1}^{y_2} l \, dy$$



on  
integrating



$y_1, y_2 \rightarrow$  functions of  $x$   
bc it changes  
for every  $x$

Finally, volume =  $\int_{x_1}^{x_2} A \, dx$  ;  $x_1, x_2 \rightarrow$  bounds of  $x$

$$\therefore V = \int_{x_1}^{x_2} \int_{y_1(x)}^{y_2(x)} \int_{z_1(x,y)}^{z_2(x,y)} dz \, dy \, dx$$

if function value changes for different places, incorporate that in the integral,

$$V = \iiint f \, dz \, dy \, dx$$



eg.  $f(x, y, z) = 1$

$$W = \{ (x, y, z) \mid x^2 + y^2 + z^2 = 1 \}$$

$$\iiint_W f \, dv = ?$$

$$z^2 = 1 - x^2 - y^2$$

$$\therefore z = \pm \sqrt{1 - x^2 - y^2} \rightarrow z \text{ bounds at } (x, y)$$

$$\therefore l = \int_{-\sqrt{1-x^2-y^2}}^{\sqrt{1-x^2-y^2}} 1 \times dz = l(x, y)$$

$$A = \int_{-\sqrt{1-x^2}}^{\sqrt{1-x^2}} l \, dy = A(x)$$

$$v = \int_a^b A \, dx$$

$$a = -1$$

$$b = 1$$

$$\therefore v = \int_{-1}^1 \int_{-\sqrt{1-x^2}}^{\sqrt{1-x^2}} \int_{-\sqrt{1-x^2-y^2}}^{\sqrt{1-x^2-y^2}} dz \, dy \, dx = \frac{4\pi}{3}$$

## Change of variables :

considers a  $U-V$  plane (a different sort of  $X-Y$  plane)

$$x = au + bv + t_1$$

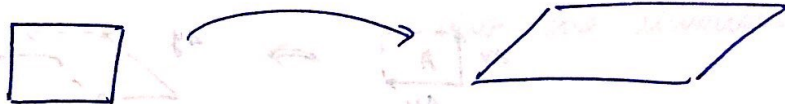
$$y = cu + dv + t_2$$

... affine linear functions

... describes the transformation

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} + \begin{pmatrix} t_1 \\ t_2 \end{pmatrix}$$

\* A square in  $UV$  plane gets transformed to a  $\parallel\text{gm}$  in  $XY$  plane.



Area of this new  $\parallel\text{gm}$  =  $\begin{vmatrix} a & b \\ c & d \end{vmatrix} \cdot \text{area of original square}$

$$x = h_1(u, v) = au + bv + t_1 ; \quad y = h_2(u, v) = cu + dv + t_2$$

$$\therefore \Delta x \sim \frac{\partial h_1}{\partial u} \Delta u + \frac{\partial h_1}{\partial v} \Delta v$$

$$\Delta y \sim \frac{\partial h_2}{\partial u} \Delta u + \frac{\partial h_2}{\partial v} \Delta v$$



OR

$$\begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix} = \begin{pmatrix} \frac{\partial h_1}{\partial u} & \frac{\partial h_1}{\partial v} \\ \frac{\partial h_2}{\partial u} & \frac{\partial h_2}{\partial v} \end{pmatrix} \begin{pmatrix} \Delta u \\ \Delta v \end{pmatrix}$$

$$J(h) = \begin{pmatrix} \frac{\partial h_1}{\partial u} & \frac{\partial h_1}{\partial v} \\ \frac{\partial h_2}{\partial u} & \frac{\partial h_2}{\partial v} \end{pmatrix} = \text{The Jacobian}$$

↓

$|J|$  = scaling factor of area from  
 $u-v$  plane to  $x-y$  plane



Theorem (Change of variables formula)

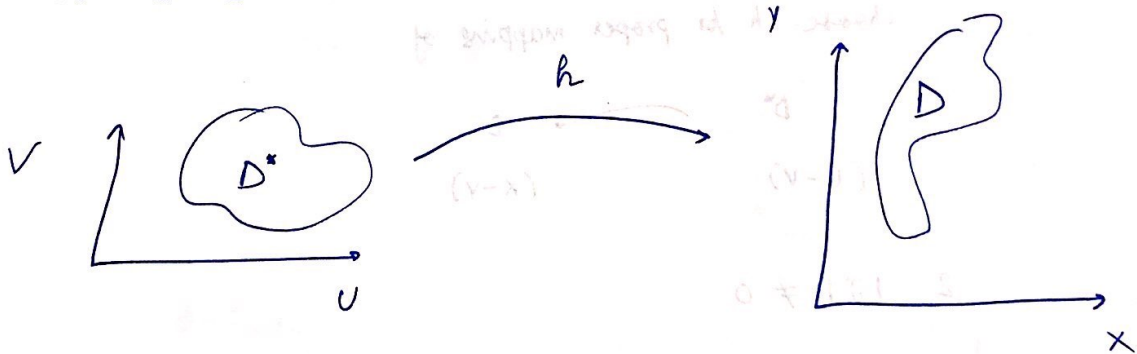
- let  $D$  be a closed & bounded subset of  $\mathbb{R}^2$  such that  $\partial D$  has content zero. Let  $f: D \rightarrow \mathbb{R}$  be continuous.
- Suppose  $\Omega$  is an open subset of  $\mathbb{R}^2$  and  $h: \Omega \rightarrow \mathbb{R}^2$  is a one-one differentiable function ( $h \rightarrow$  transformation matrix)

$$h = (h_1, h_2)$$

$\downarrow$   $\hookrightarrow$   $x$  transform  
 $x$  transform

where  $h_1$  &  $h_2$  have continuous partial derivatives in  $\Omega$   
 &  $\det |J| \neq 0 \rightarrow$  would transform U-V plane into one dimension

- let  $D^* \subset \Omega$  such that  $h(D^*) = D$



then

$$\iint_D f(x,y) dx dy = \iint_{D^*} (f \circ h)(u,v) |J(h)(u,v)| du dv$$

$\hookrightarrow$  scaling factor of  $dA$

Integral in  $xy$  plane on original area = Integral in  $u-v$  plane on transformed area



\* For  $|J|$  we write  $\frac{\partial(x,y)}{\partial(u,v)} = \frac{dA_{xy}}{dA_{uv}}$

\*  $UV \xrightarrow{J} XY$

$\therefore dA_{xy} = |J| dA_{uv}$

$|J| = \frac{dA_{xy}}{dA_{uv}}$

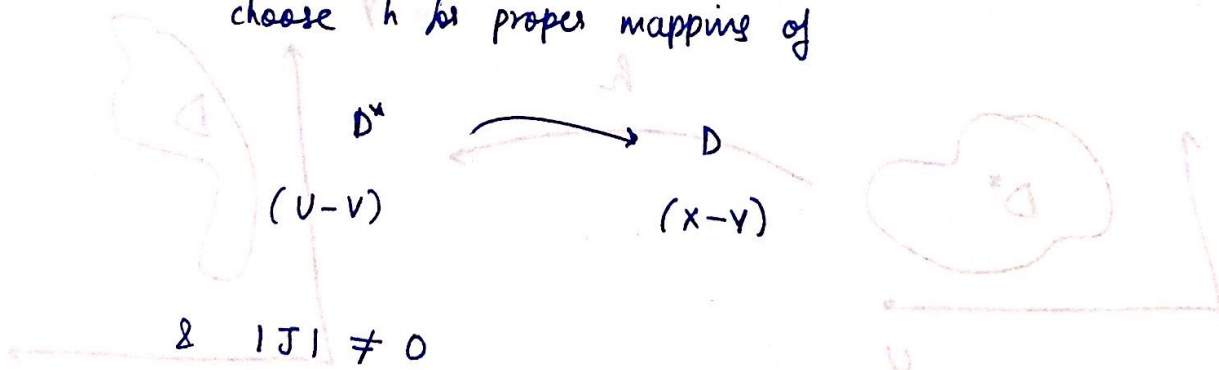
$\therefore \iint_D f dx dy = \iint_{D^*} f(x(u,v), y(u,v)) |J| du dv$

\* For polar coordinates:

$\frac{\partial(x,y)}{\partial(r,\theta)} = \begin{vmatrix} r \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r$

\* For change of variables:

choose  $h$  for proper mapping of



Boundary of  $D^*$  in  $uv \approx$  Boundary of  $D$  in  $xy$

\* in 3D:

$$\iiint_P f dV = \iiint_{P^*} f |J| dV^*$$

$$|J| = \frac{\partial(x, y, z)}{\partial(u, v, w)} = \frac{dV_{xyz}}{dV_{uvw}}$$

$$= \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix}$$

\* Spherical jacobian in 3D:

$$|J| = r^2 \sin \phi$$

$$\begin{array}{ccc} dV_{xyz} & = & dV_{r, \theta, \phi} \cdot |J| \\ \downarrow & & \downarrow \\ dx dy dz & & dr d\theta d\phi \cdot r^2 \sin \phi \end{array}$$

$$\begin{aligned} \therefore V \text{ of sphere} &= \int_0^{2\pi} \int_0^{\pi} \int_0^R r^2 dr \cdot \sin \theta d\theta \cdot d\phi \\ &= \frac{4\pi}{3} \end{aligned}$$



\* in cylindrical:

$$x = r \cos \theta$$

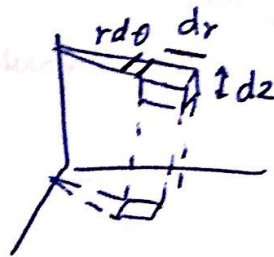
$$y = r \sin \theta$$

$$z = z$$

$$|J| = r \quad (\text{on computing})$$

$$\text{and } dV_{xyz} = dx \cdot dy \cdot dz$$

$$dV_{r,\theta,z} = dr \cdot d\theta \cdot dz \cdot r$$



∴ clearly, ratio = r

\* convert to diff systems to make  $\int$  easy

↳ cartesian

↳ spherical

↳ cylindrical

↳ polar

some values of jacobians:

\* spherical:

$$dx dy dz = \underline{r^2 \sin \phi} \quad dr d\phi d\theta$$

\* polar:

$$dx dy = \underline{r} dr d\theta$$

\* cylindrical:

$$dx dy dz = \underline{r} dr d\theta dz$$


Vector & scalar fields:

\* A vector field  $\vec{F}$  is a conservative vector field if it is a gradient of some scalar function i.e. there exists a diff. scalar fn.

$f$  such that  $\vec{F} = \nabla f$

Curves & paths:

• they are continuous maps from  $[a, b] \rightarrow \mathbb{R}^n$

  
a path where each point corresponds to some  $n$  dimensional output



→ cont. if all its one dimensional mappings are individually cont.

→ closed path  $\Rightarrow c(a) = c(b)$

→ simple path  $\Rightarrow c(t_1) \neq c(t_2)$

↳ parameter

for any  $t_1, t_2$

Line integrals of vector fields:

$$\int_C \mathbf{F} \cdot d\mathbf{s} = \int_a^b \mathbf{F}(c(t)) \cdot \mathbf{c}'(t) dt$$

dot product of vector at that pt.

w/ tangent vector of path

$t$  is the parameter to traverse  $[a, b]$

- convert everything to  $t$  and then  $\int$

$$\int_C \mathbf{F} \cdot d\mathbf{s} = \int_a^b F_x dx + \int_a^b F_y dy + \int_a^b F_z dz$$

... cos of dot product

eg.  $\int_C x^2 dx + xy dy + dz$

$C: [0,1] \rightarrow \mathbb{R}^3, \quad c(t) = \langle t, t^2, 1 \rangle$

$F = \langle x^2, xy, 1 \rangle$

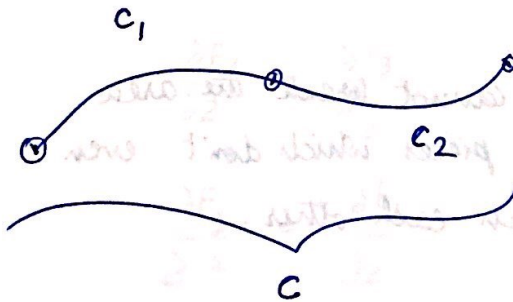
$F(c(t)) = \langle t^2, t^3, 1 \rangle$

$c'(t) = \langle 1, 2t, 0 \rangle$

$\therefore \int_C F \cdot ds$

$= \int_0^1 (t^2 + 2t^4) dt = 11/15$

\*



$\int_C F \cdot ds = \int_{C_1} F \cdot ds + \int_{C_2} F \cdot ds$



\* you can reparameterise a path in many ways,  
but if you start navigating it ~~to~~ in reverse,  
please put a minus sign!

\* Reparameterisation fn. must be bijective & its  
inverse also!

FTC:

$$\int_C \nabla f \cdot d\vec{s} = f(c(b)) - f(c(a))$$

$$\oint \nabla f \cdot d\vec{s} = 0 \quad (\text{closed curve})$$

→ independent of path  
→ only depend on endpoints.

Connected means: you cannot break the area  
into pieces which don't even  
touch each other.

Path connected: if you can draw even a single  
path b/w any two pts. such that  
the entire path lies inside the domain,  
then it is path connected.

Path connected  $\implies$  connected

connected  $\not\Rightarrow$  path connected

\* For a given continuous vector field  $\vec{F}$  in  $\mathbb{R}^n$  defined on  $D$ , an open, path connected subset of  $\mathbb{R}^n$  the vector field  $\vec{F}$  is a conservative field if and only if

$\int_C \vec{F} \cdot d\vec{s}$  is independent of path in  $D$ .  
(in  $D$ )

\* conditions for cons. fields: (Necessary but not sufficient)

$\vec{F} = \langle F_1, F_2, F_3 \rangle$  & is a conservative vector field then, in  $D$  where  $F_1, F_2, F_3 \in C^1$

$$\frac{\partial F_1}{\partial y} = \frac{\partial F_2}{\partial x} \quad D = \text{open}$$

$$\frac{\partial F_2}{\partial z} = \frac{\partial F_3}{\partial y}$$

$$\frac{\partial F_3}{\partial x} = \frac{\partial F_1}{\partial z}$$

\* converse is partially true under some additional hypothesis on  $D$ .



Simply connected: area w/ no holes & can't consist of 2 or more pieces

\* Sufficient condition for cons fields:

$D = \text{open} + \text{simply connected}$   
same cond. as 64.

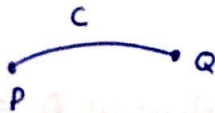
Summary:

for a given vector field  $\vec{F} : D \subset \mathbb{R}^n$  ;  $n=2,3$

1. if  $F$  is a cont, conservative v.f. i.e.  $\vec{F} = \nabla f \rightarrow$  some scalar  $f$ , then

$$\int_C \vec{F} \cdot ds = f(P) - f(Q)$$

... independent of path,  
only depends on  
endpt.



2. let  $F$  be a cont. field &  $D$  be an open connected set in  $\mathbb{R}^n$ .

Then  $F$  is a conservative field if and only if the line integral of  $F$  is path independent in  $D$ .

3. if  $F = \text{cons.}$

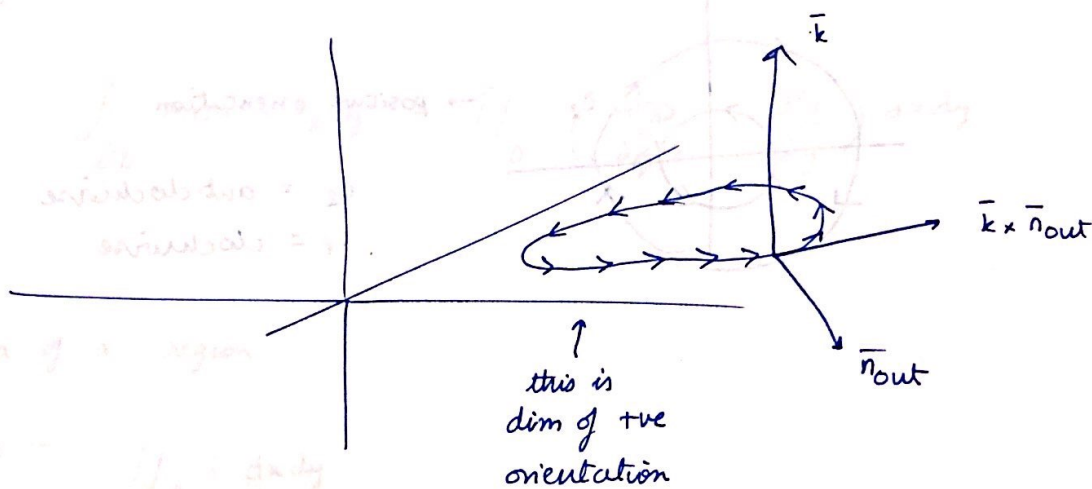
$$\frac{\partial F_1}{\partial y} = \frac{\partial F_2}{\partial x}$$

4. let  $D$  be an open, simply connected region in  $\mathbb{R}^2$

$F$  is cons. if & only if

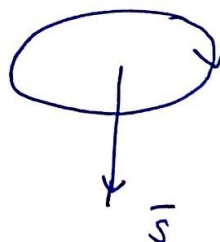
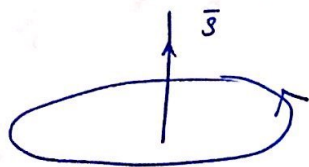
$$\frac{\partial F_1}{\partial y} = \frac{\partial F_2}{\partial x}$$

\* direction of positive orientation:  $\vec{d} = \vec{k} \times \vec{n}_{out}$



(while traversing the curve,  
the enclosed area is always  
on your left  
→ anticlockwise)

∴ orientation of boundary induces orientation of area.



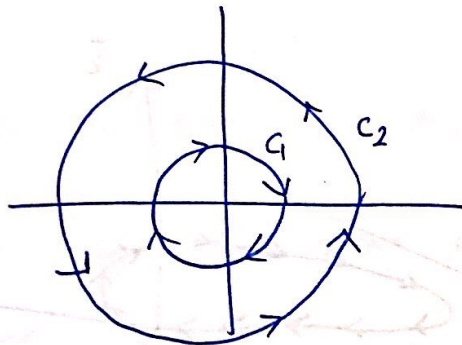


\* compare  $c'(t)$  with  $\bar{k} \times \bar{n}_{out}$  to see if you are traversing +ve ly or -ve ly.

$$c'(t) = \bar{k} \times \bar{n}_{out} = +ve$$

$$c'(t) = -\bar{k} \times \bar{n}_{out} = -ve$$

eg.



→ positive orientation

$c_2$  = anticlockwise

$c_1$  = clockwise

### Green's Theorem:

1. Let  $D$  be a bounded region in  $\mathbb{R}^2$  with a positively oriented boundary  $\partial D$  consisting of a finite no. of non intersecting simple closed curves piecewise  $C^1$  curves.
2. Let  $\Omega$  be an open set in  $\mathbb{R}^2$  such that  $(D \cup \partial D) \subset \Omega$  and let  $F_1: \Omega \rightarrow \mathbb{R}$  &  $F_2: \Omega \rightarrow \mathbb{R}$  be  $C^1$  fns.

Then,

$$\int_{\partial D} F_1 dx + F_2 dy = \iint_D \left( \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy$$

\* Area of a region:

$$A = \iint_D 1 \, dx dy$$

↳ so choose  $F_1$  &  $F_2$  such that

$$\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} = 1$$

$$\therefore A = \frac{1}{2} \int_C x dy - y dx$$

$$= \int_C x dy$$

$$= - \int_C y dx$$



\* in polar coords:

$$A = \iint |dx dy|$$

$$= \frac{1}{2} \int_C x dy - y dx$$

$$= \frac{1}{2} \int_C \left( x(t) \frac{dy}{dt} - y(t) \frac{dx}{dt} \right) dt$$

$$x = a \cos t$$

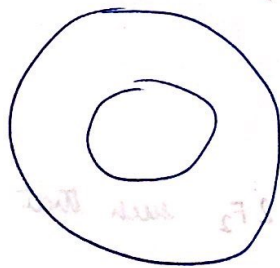
$$y = a \sin t$$

⇒ simplifies to

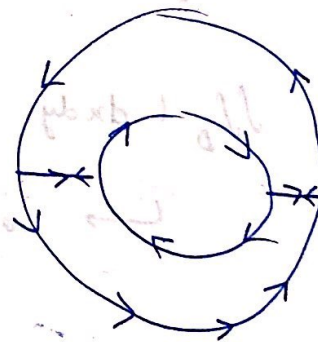
$$\int_C \frac{1}{2} r^2 d\theta$$

= area of  $v$  small  
segment at  $(r, \theta)$   
summed up.

\* for edgy areas, break them up:



=



line integrals along  
induced boundaries cancel

Del operator:

$$\nabla = \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k}$$

$$\text{curl } \vec{F} = \nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix}$$

$$\vec{F} = \langle F_1, F_2, F_3 \rangle$$

\* For an object in a velocity vector field in XY plane

$$\nabla \times \vec{v} = 2\vec{\omega}$$

curl = 2 × angular velocity about  $\hat{k}$  z axis

\*  $\nabla \times \vec{F} = 0 \Rightarrow$  fluid has no rigid rotations  
= curl free  
= irrotational



$$\text{let } F = \nabla f$$

$$\therefore \nabla \times F = \nabla \times \nabla f = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \end{vmatrix}$$

$$= i \left( \frac{\partial^2 f}{\partial y \partial z} - \frac{\partial^2 f}{\partial z \partial y} \right) = 0$$

$$+ j \left( \frac{\partial^2 f}{\partial z \partial x} - \frac{\partial^2 f}{\partial x \partial z} \right) = 0$$

$$+ k \left( \frac{\partial^2 f}{\partial x \partial y} - \frac{\partial^2 f}{\partial y \partial x} \right) = 0$$

because  $f$  is  $C^2$

$$\therefore \nabla \times F = 0 \quad \text{for gradient field}$$

$$\text{curl } F = 0$$

Green's theorem - curl edition!

$$\int_{\partial D} \vec{F} \cdot d\vec{s} = \iint_D (\text{curl } \vec{F} \cdot \vec{k}) \, dx \, dy$$

$$\vec{F} = \langle F_1, F_2 \rangle$$

$D$  - open + connected

$\partial D$  - positively oriented

Conservative field & its curl:

Theorem:

1. let  $\Omega$  be an open, simply connected region in  $\mathbb{R}^2$
2. if  $\vec{F} = F_1 \hat{i} + F_2 \hat{j}$  is such that  $F_1$  &  $F_2$  have continuous first order partial derivatives on  $\Omega$ .

then  $F$  is a cons. field in  $\Omega$  if and only if

$$\boxed{\nabla \times \vec{F} = 0} \quad \text{in } \Omega$$

$$\begin{aligned} \text{curl } \vec{F} = 0 & \not\Rightarrow \text{gradient field} \\ \text{gradient field} & \Rightarrow \text{curl } \vec{F} = 0 \end{aligned}$$



## Divergence of a vector field:

$$\operatorname{div} F = \nabla \cdot \vec{F} = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} \quad ; \quad F = \langle F_1, F_2, F_3 \rangle$$

\* divergence of any curl is 0

$$\nabla \cdot (\nabla \times \vec{G}) = 0 \quad \text{if } \vec{G} \text{ is a } C^2 \text{ vector field}$$

## Green's theorem - Divergence edition!

$$\int_{\partial D} \vec{F} \cdot \vec{n} \, ds = \iint_D \nabla \cdot \vec{F} \, dx \, dy$$

$$\vec{T}(t) = \frac{c'(t)}{\|c'(t)\|} \quad \text{— tangent unit vector}$$

$$\vec{n} = \vec{T} \times \vec{k} \quad \text{— normal unit vector}$$

## Surfaces:

Let  $D$  be a path connected subset in  $\mathbb{R}^2$ . A parameterised surface is a continuous fn  $\phi: D \rightarrow \mathbb{R}^3$

$$\phi(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle$$

$\overline{\nabla \phi}_u$  = partial derivative along  $u$  axis (for fixed  $v_0$ )

$$\overline{\nabla \phi} \cdot (1, 0)$$

$$= \frac{\partial \phi}{\partial u} = \left\langle \frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u} \right\rangle$$

$\overline{\nabla \phi}_v$  = partial derivative along  $v$  axis (for fixed  $u_0$ )

$$= \overline{\nabla \phi} \cdot (0, 1)$$

$$= \frac{\partial \phi}{\partial v} = \left\langle \frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, \frac{\partial z}{\partial v} \right\rangle$$

these are the tangents along 2 dirns.

$\therefore$  they lie in tangent plane

$$\therefore \bar{n}_T = \overline{\nabla \phi}_u \times \overline{\nabla \phi}_v$$

$\&$   $\Pi$ : tangent plane =  $(x, y, z)$ :

$$\bar{n}_{(u_0, v_0)} \cdot \langle (x - x_0), (y - y_0), (z - z_0) \rangle = 0$$

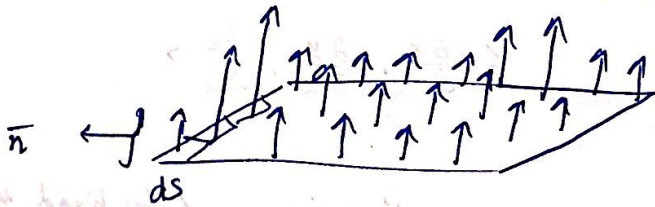


- \* Non-singular surface: non-zero  $\bar{n}$
- singular surface:  $\bar{n} = \text{null vector}$

$$* \text{Area}(\phi) = \iint_E \|\bar{\phi}_u \times \bar{\phi}_v(u, v)\| \, du \, dv$$

$\phi$ : function from  $E$  in  $\mathbb{R}^2$  to  $\mathbb{R}^3$

$\|\bar{\phi}_u \times \bar{\phi}_v\| = \text{normal vector magnitude for area } dS = du \, dv$



since:

(i)  $\partial E$  is of content zero

(ii)  $\bar{\phi}_u \times \bar{\phi}_v \rightarrow \text{cont. on } E$

$\hookrightarrow$  integral is well defined

$$dS = \|\bar{\phi}_u \times \bar{\phi}_v\| \, du \, dv$$

$$\therefore \text{Area} = \iint dS$$

$$d\vec{S} = \vec{\phi}_u \times \vec{\phi}_v$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & \frac{\partial z}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & \frac{\partial z}{\partial v} \end{vmatrix}$$

$$|dS| = \sqrt{x_{ds}^2 + y_{ds}^2 + z_{ds}^2}$$

Surface integral of a vector field:

$F$ : bounded vector field on  $\mathbb{R}^3$

domain of  $F$  contains the regular nonparameterised surface  $\phi: E \rightarrow \mathbb{R}^3$ , then the surface integral of  $F$

over  $S$  is

$$\iint_S \vec{F} \cdot d\vec{S} = \iint_E \vec{F}(\phi(u,v)) \cdot (\vec{\phi}_u \times \vec{\phi}_v) \, du \, dv$$

$$= \iint_E \vec{F} \cdot \hat{n} \, dS = \iint_E \dots$$



\* How to solve qs:

write surface as  $\langle x, y, z \rangle = \langle f_1, f_2, f_3 \rangle$

$\nabla P_x =$  change vector along x

$$= \left\langle \frac{\partial f_1}{\partial x}, \frac{\partial f_2}{\partial x}, \frac{\partial f_3}{\partial x} \right\rangle$$

$\nabla P_y =$  "

$$= \left\langle \frac{\partial f_1}{\partial y}, \frac{\partial f_2}{\partial y}, \frac{\partial f_3}{\partial y} \right\rangle$$

$$\bar{n} = \nabla P_x \times \nabla P_y$$

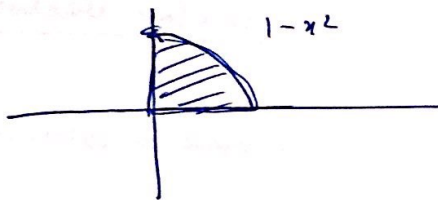
$$\bar{F} = \langle F_1, F_2, F_3 \rangle$$

$F_1 =$  function of  $\langle x, y, z \rangle$

$F_2 =$

$F_3 =$

$$\iint \bar{F} \cdot d\bar{s} = \iint \langle F_1, F_2, F_3 \rangle \cdot \langle \nabla P_x \times \nabla P_y \rangle dx dy$$



\* Reparameterising surfaces:

- magnitude will stay same
- sign may change

let  $\phi: E \rightarrow \mathbb{R}^3$  be a smooth parameterised surface.

Suppose  $\tilde{\phi} = \phi \circ h$  is a repara. of  $\phi$ .

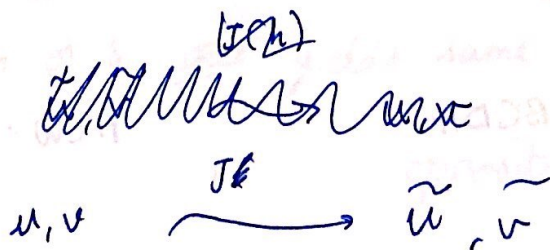
How do the normal vectors (and the area they denote) transform?

$$(\tilde{\Phi}_{\tilde{u}} \times \tilde{\Phi}_{\tilde{v}})(\tilde{u}, \tilde{v}) = (\phi_u \times \phi_v)(u, v) \times \begin{matrix} \text{scaling factor} \\ \parallel \\ |J(h)(\tilde{u}, \tilde{v})| \end{matrix}$$

↓  
Area in  $\tilde{u}-\tilde{v}$  space

$$(u, v) = (h(\tilde{u}, \tilde{v}))$$

↓  
Area in  $u-v$  space



$$A_{uv} = \frac{A_{\tilde{u}\tilde{v}}}{|J|}$$



if  $J > 0$  :

$$\iint_{\tilde{\phi}} \vec{F} \cdot d\vec{s} = \iint_{\phi} \vec{F} \cdot d\vec{s}$$

if  $J < 0$  :

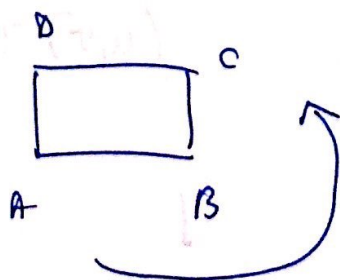
$$\iint_{\tilde{\phi}} \vec{F} \cdot d\vec{s} = - \iint_{\phi} \vec{F} \cdot d\vec{s}$$

\* if  $\tilde{\phi}(\tilde{u}, \tilde{v}) = \phi(v, u)$  (variable exchange)

the new surface is called  
'opposite' of the old one

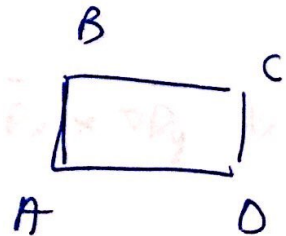
$$\iint_{\text{opp}} \vec{F} \cdot d\vec{s} = - \iint_{\phi} \vec{F} \cdot d\vec{s}$$

$$\rightarrow (\phi^{\text{opp}})^{\text{opp}} = \phi$$



ACW : ABCDA

opposite



ACW : ADCBA

## orientable surfaces:

\* Parametrised surface:

$$\hat{n}(u, v) = \frac{\overline{\phi_u} \times \overline{\phi_v}}{\|\overline{\phi_u} \times \overline{\phi_v}\|}$$

↓  
normal unit vector at a pt  $(u, v)$

$$\phi_u = \left( \frac{\partial f_x}{\partial u}, \frac{\partial f_y}{\partial u}, \frac{\partial f_z}{\partial u} \right)$$
$$\phi_v = \left( \frac{\partial f_x}{\partial v}, \frac{\partial f_y}{\partial v}, \frac{\partial f_z}{\partial v} \right)$$

\* implicit surface:

$$F(x, y, z) = 0$$

$$\text{normal unit vector } \hat{n} = \frac{\nabla F(P)}{\|\nabla F(P)\|}$$

$P$  is a pt. where we are finding  $\hat{n}$

\* if there exists a cont. fn. which can spit out a normal vector at every pt. on inputting that point

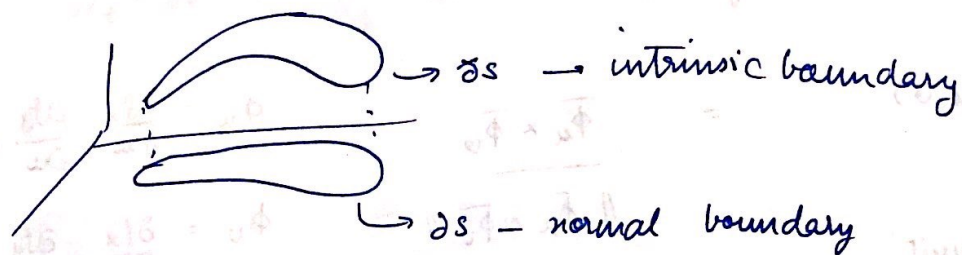
then we say that the surface is orientable

if a param. of  $S$  ~~gives~~ yields same  $\hat{n}$  = ori-preserved

" " opposite  $\hat{n}$  = ori-reversed



## Intrinsic boundary



## Stokes Theorem:

let  $S$  be piecewise  $C^2$

bounded

oriented (imp.) surface in  $\mathbb{R}^3$

whose piecewise smooth intrinsic boundary  $\partial S$  consists of a finite no. of non-intersecting simple closed curves along w/ induced orientation

$F =$  smooth vector field

$$\int_{\partial S} \vec{F} \cdot d\vec{r} = \iint_S \text{curl } \vec{F} \cdot d\vec{S}$$

\* To find area:

$$\iint_S \sqrt{1+z_x^2+z_y^2} \, dx \, dy$$

$$z_x = \frac{\partial z}{\partial x} \quad z_y = \frac{\partial z}{\partial y}$$

$$z = f(x, y)$$

OR  $\iint_S \sqrt{1+y_x^2+y_z^2} \, dx \, dz$

$$y = f(x, z)$$

Surface integrals of  $\vec{F}$  are independent if

$$\iint_{\phi} \vec{F} \cdot d\vec{s} = \iint_{\hat{\phi}} \vec{F} \cdot d\vec{s}$$

$\phi, \hat{\phi}$  lie in  $D$

& have same intrinsic boundary & same orientation

\* How to check if  $F$  is a curl field?

~~is~~ necessary

BUT NOT

sufficient  
condition

$$\text{div } F = 0$$

↳ simply connected domain



## Consequences of Stokes Theorem:

$F$  - smooth vector field on an open subset  $D$  of  $\mathbb{R}^3$   
such that  $\text{curl } F = 0$  on  $D$

(i) Suppose  $S$  is a bounded oriented piecewise  $C^2$  surface  
in  $D$ ,  $\partial S$  - intrinsic boundary

$$\int_{\partial S} \bar{F} \cdot d\bar{r} = 0$$

$$\text{If } \partial S = C_1 - C_2, \quad \partial S = C_1 \cup C_2$$

$$C_1 = -C_2$$

$$\int_{C_1} \bar{F} \cdot d\bar{r} = \int_{C_2} \bar{F} \cdot d\bar{r}$$

(ii) if  $D$  is simply connected,  $F = \nabla f$

\* if  $\partial S = \emptyset$  (null)

$\partial S$  - i.b of surface  $S$

$$\Rightarrow \iint \text{curl } \bar{F} \cdot d\bar{S} = 0$$

## Gauss Divergence Theorem:

Let  $D$  be a closed & bounded subset of  $\mathbb{R}^3$  whose boundary  $\partial D$  consists of a finite no. of non intersecting piecewise smooth surfaces w/o any edges & is +vely oriented.

Let  $F$  be a smooth vector field in  $D$ .

$$\iint_{\partial D} \vec{F} \cdot d\vec{S} = \iiint_D (\text{div } \vec{F}) dx dy dz$$

To find volume:

choose  $F$  so that  $\text{div } F = 1$

$$F = \left\langle \frac{x}{3}, \frac{y}{3}, \frac{z}{3} \right\rangle$$

$$\therefore V = \iint_{\partial D} \vec{F} \cdot d\vec{S}$$

$$= \iint \left[ \frac{x}{3} \|\phi_y \times \phi_z\| dy dz + \frac{y}{3} \|\phi_x \times \phi_z\| dx dz + \frac{z}{3} \|\phi_x \times \phi_y\| dx dy \right]$$

$$\hookrightarrow \det \begin{bmatrix} x & y & z \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & \frac{\partial z}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & \frac{\partial z}{\partial v} \end{bmatrix} = d(u, v)$$



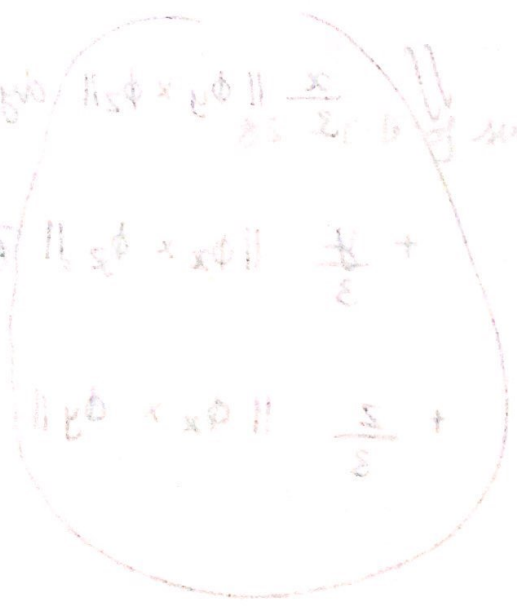
that is called the Wronskian

$$\text{vol} = \frac{1}{3} \iint_E W(x, y, z)(u, v) d(u, v)$$

\* if  $\iint F \cdot d\vec{S}$  is a lengthy calc, maybe  $\iiint \text{div } F \cdot dv$  can be shorter

\*  $F$  is smooth vector field on an open subset containing a closed and bounded subset  $D$  of  $\mathbb{R}^3$  such that  $\text{div } F = 0$  on  $D$  & if  $\partial D$  consists of finite nonintersecting closed piecewise smooth surfaces, oriented by outward normals

$$\iiint_{\partial D} F \cdot d\vec{S} = 0$$

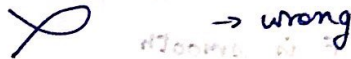


MA III formula sheet:

\* closed path: start pt. = end pt.  
 $c(a) = c(b)$

where parameter  $\in [a, b]$

\* simple path: path does not intersect itself



\* connected area: you cannot break the area into pieces which don't even touch each other

\* path connected: for any two pts. in that domain (all possible pairs), if you can draw at least one path connecting them which lies entirely in the domain, then its path connected

path connected  $\rightarrow$  connected

connected  $\nrightarrow$  path connected

\* simply connected: area w/ no holes & cannot consist of two or more pieces

simply connected  $\rightarrow$  path connected + connected

path connected  $\nrightarrow$  simply connected

connected  $\nrightarrow$



\* condition for cons. field:  $\text{curl } F = 0$

$D$  - area on which  $F$  is defined must be  
 open  
 simply connected

$F$  is smooth

$\text{curl } F = 0 \rightarrow F$  is cons.  
 $F$  is cons.  $\rightarrow \text{curl } F = 0$

\* dir of +ve orientation  $\vec{d}\vec{r} = \vec{k} \times \vec{n}$  out

(area will be on left)

\* Green's Theorem / Stokes Theorem:

$$\int_C \vec{F} \cdot d\vec{r} = \iint_S \text{curl } \vec{F} \cdot d\vec{S} ; C = \partial S$$

conditions: simply connected

on  $S$ : - bounded region in  $\mathbb{R}^2$

- positively oriented boundary (very very imp)

$C$  - consists of finite

non intersecting  
 simple  
 closed  
 piecewise  $C_1$  curves

$$F = \langle F_1, F_2 \rangle$$

$$F_1, F_2 \rightarrow C_1 \text{ fns.}$$

$$\text{Area} = \frac{1}{2} \int_C x dy - y dx$$

$$= \int_C x dy = - \int_C y dx$$

$$\star \nabla \times \nabla f = 0$$

$$\nabla \times \vec{F} = 0 \quad \text{if } F \text{ is a gradient field}$$

$$\star \nabla \cdot (\nabla \times \vec{G}) = 0 \quad \text{if } G \text{ is a } C^2 \text{ vector field}$$

div. of any curl is 0

$\star$  Green's theorem - Divergence form:

$$\int_{\partial D} \vec{F} \cdot \vec{n} \, ds = \iint_D \nabla \cdot \vec{F} \, dx dy$$

$\star$  Surface parameterised by  $\langle u, v \rangle$ :

$$\vec{dS}_{uv} = \overline{\phi_u \times \phi_v} \cdot du dv$$

$$\text{Area} = \iint_E \|\vec{dS}\| \rightarrow \text{when } \partial E \text{ is of content zero}$$

$$\phi_u \times \phi_v \rightarrow \text{cont. on } E$$



$$\hat{n} = \frac{\nabla F(P)}{\|\nabla F(P)\|}$$

\* surface is orientable if assignment of normals for every  $dS$  is cont. throughout the surface.

\* Sufficient condition to check if  $F$  is a curl field:

•  $\text{div } F = 0$

• domain is simply connected

\* Gauss Divergence Theorem:

$$\iint_{\partial D} \vec{F} \cdot d\vec{S} = \iiint_D \text{div } F \, dV$$

conditions:

on  $D$ : closed (boundary pts. are part of set)  
 bounded subset of  $\mathbb{R}^3$

on  $\partial D$ : **POSITIVELY ORIENTED**

consists of finite  
 non intersecting  
 piecewise smooth surfaces w/o any edges

on  $F$ : smooth vector field on  $D$ .

$$V = \frac{1}{3} \int_E \begin{vmatrix} x & y & z \\ \frac{dx}{du} & \frac{dy}{du} & \frac{dz}{du} \\ \frac{dx}{dv} & \frac{dy}{dv} & \frac{dz}{dv} \end{vmatrix} du dv$$

$A \cdot B = (AB)^T = B^T \cdot A^T$   
 $A \cdot B = (AB)^T \Rightarrow B^T \cdot A^T = (AB)^T$   
 $A \cdot B = (AB)^T \Rightarrow B^T \cdot A^T = (AB)^T$

Anticommutative property:  $AB \neq BA$   
 Multiplication for matrices:  $AB = BA$

$$A^T B^T = (BA)^T$$

Scaling matrix: (inner product / scalar product) :  $AB = BA$

defined for two column vectors of same size  
 $\rightarrow$  represent pts in  $R^n$

$$\begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ w_n \end{bmatrix} = w \quad \text{and} \quad \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = v$$