

PH111: Tutorial Sheet 3 Solutions

This tutorial sheet contains problems related to work-energy theorem, conservative force, and potential energy.

1. Mass m rotates on a frictionless table, held to circular path by a string which passes through a hole in the table. The string is slowly pulled through the hole so that the radius of the circle changes from R_0 to R_1 . Show that the work done in pulling the string equals the increase in kinetic energy of the mass.

Soln: We know that the radial component of acceleration is given by

$$a_r = \ddot{r} - r\dot{\theta}^2.$$

Here the mass is being pulled very slowly so $\ddot{r} \approx 0$, therefore, the only acceleration experienced by the mass is the centripetal acceleration

$$a_r \approx -r\dot{\theta}^2 = -r\omega^2.$$

If the particle is pulled slowly, the force applied is the tension in the string which should be the centripetal force

$$F = T = -m\omega^2 r,$$

so that the work done will be

$$W = \int_{R_0}^{R_1} F dr = -m \int_{R_0}^{R_1} \omega^2 r dr.$$

r dependence of ω can be calculated using the fact that the angular momentum of the particle about the center of the circle will be conserved because F being radial, does not impart any torque to the particle, with respect to the center. Assuming that the initial angular velocity of the mass was ω_0 corresponding to the radius R_0 , conservation of angular momentum ($I\omega = mr^2\omega$), implies

$$\begin{aligned} mR_0^2\omega_0 &= mr^2\omega \\ \implies \omega(r) &= \frac{R_0^2\omega_0}{r^2}, \end{aligned}$$

using this we have

$$W = - \int_{R_0}^{R_1} \omega^2 r dr = -m\omega_0^2 R_0^4 \int_{R_0}^{R_1} \frac{r dr}{r^4} = -m\omega_0^2 R_0^4 \int_{R_0}^{R_1} \frac{dr}{r^3} = \frac{1}{2} m\omega_0^2 R_0^4 \left(\frac{1}{R_1^2} - \frac{1}{R_0^2} \right)$$

Increase in kinetic energy of the particle will be

$$\Delta K = \frac{1}{2} I_1 \omega_1^2 - \frac{1}{2} I_0 \omega_0^2 = \frac{1}{2} \left\{ mR_1^2 \left(\frac{R_0^4 \omega_0^2}{R_1^4} \right) - mR_0^2 \omega_0^2 \right\} = \frac{1}{2} m\omega_0^2 R_0^4 \left(\frac{1}{R_1^2} - \frac{1}{R_0^2} \right),$$

which is same as the expression for W above.

2. A particle of mass m moves in one dimension along the positive x axis. It is acted on by a constant force directed towards the origin with the magnitude B , and an inverse law repulsive force of magnitude A/x^2 .

- (a) Find the potential energy function $V(x)$

Soln: The force is given by

$$\mathbf{F} = \left(-B + \frac{A}{x^2}\right) \hat{\mathbf{i}}, \text{ for } x \geq 0.$$

If $U(x)$ is the potential energy, then for $x \geq 0$

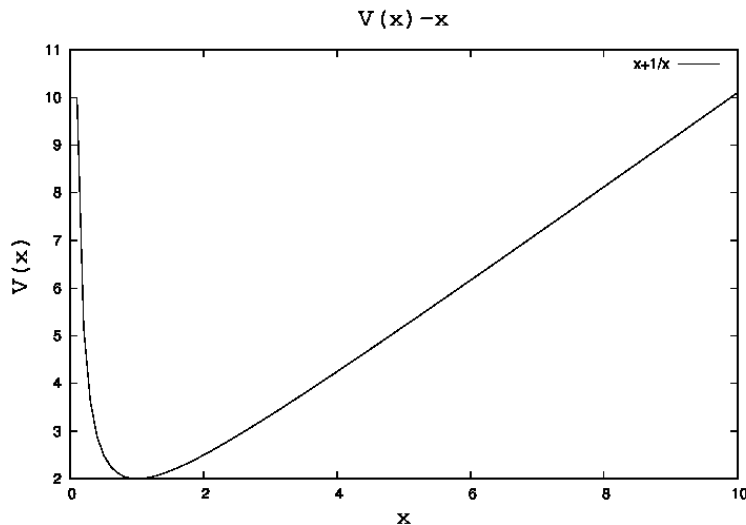
$$\begin{aligned} -\frac{dV}{dx} &= -B + \frac{A}{x^2} \\ \implies V(x) &= Bx + \frac{A}{x} + C, \end{aligned}$$

where C is a constant, which we can set to zero so

$$V(x) = Bx + \frac{A}{x}$$

- (b) Plot the potential energy as a function of x , and the total energy of the system, assuming that the maximum kinetic energy is $K_0 = \frac{1}{2}mv_0^2$.

Soln: The plot of the potential energy for $A = B = 1$ is



The minimum of potential energy can be obtained

$$\begin{aligned} \frac{dV}{dx} &= B - \frac{A}{x^2} = 0 \\ \implies x &= \sqrt{\frac{A}{B}}, \end{aligned}$$

for which $V = B\sqrt{\frac{A}{B}} + A\sqrt{\frac{B}{A}} = 2\sqrt{AB}$. Because total energy is conserved, therefore, $E = K + V = \text{constant}$. Thus, when we have maximum kinetic energy,

we will have minimum potential energy, implying that $E = K_{max} + V_{min} = \frac{1}{2}mv_0^2 + 2\sqrt{AB}$. Therefore, total energy of the particle can be represented by a horizontal line in the plot, corresponding to $V(x) = \frac{1}{2}mv_0^2 + 2\sqrt{AB}$.

- (c) What is the point of equilibrium, i.e., the point where net force acting on the particle is zero.

Soln: Point of equilibrium is obtained by

$$F = -B + \frac{A}{x^2} = 0$$

$$\implies x = \sqrt{\frac{A}{B}},$$

which is the same point where the potential energy is minimum.

3. A particle of mass M is held fixed at the origin. The gravitational potential energy of another particle of m , in the field of the first mass, is given by

$$V(\mathbf{r}) = -\frac{GMm}{r},$$

where G is the gravitational constant, and r is the distance of mass m from the origin.

- (a) What is the force acting on the particle of mass m ?

Soln: Here

$$V(\mathbf{r}) = -\frac{GMm}{r} = -\frac{GMm}{\sqrt{x^2 + y^2 + z^2}}$$

$$\implies \mathbf{F}(\mathbf{r}) = -\nabla V(\mathbf{r})$$

$$= GMm \left(\frac{\partial}{\partial x} \frac{1}{\sqrt{x^2 + y^2 + z^2}} \hat{\mathbf{i}} + \frac{\partial}{\partial y} \frac{1}{\sqrt{x^2 + y^2 + z^2}} \hat{\mathbf{j}} + \frac{\partial}{\partial z} \frac{1}{\sqrt{x^2 + y^2 + z^2}} \hat{\mathbf{k}} \right)$$

$$= -GMm \left(\frac{x\hat{\mathbf{i}} + y\hat{\mathbf{j}} + z\hat{\mathbf{k}}}{(x^2 + y^2 + z^2)^{3/2}} \right) = -\frac{GMm\mathbf{r}}{r^3} = -\frac{GMm\hat{\mathbf{r}}}{r^2}$$

- (b) Calculate the curl of this force.

Soln: Because for this force a potential energy function exists, its curl must vanish. We calculate it as

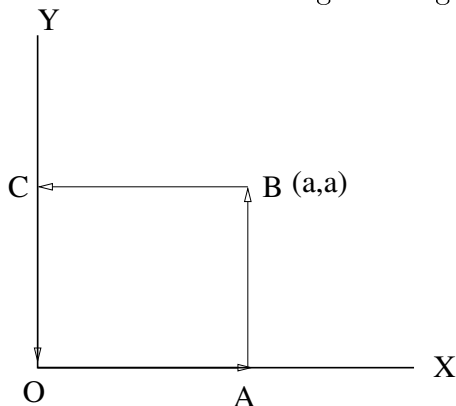
$$\nabla \times \mathbf{F} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{x}{(x^2 + y^2 + z^2)^{3/2}} & \frac{y}{(x^2 + y^2 + z^2)^{3/2}} & \frac{z}{(x^2 + y^2 + z^2)^{3/2}} \end{vmatrix}$$

$$= -3 \left(\frac{yz - yz}{(x^2 + y^2 + z^2)^{5/2}} \right) \hat{\mathbf{i}} + \dots = 0$$

4. Consider a 2D force field $\mathbf{F} = A(y^2\hat{\mathbf{i}} + 2x^2\hat{\mathbf{j}})$. Calculate the work done by this force in going around a closed path which is a square made up of sides of length a , lying in

the xy -plane, with two of its vertices located at the origin, and point (a, a) . Find the answer by doing the line integral, as well as by using the Stokes' theorem. The path is traversed in a counter clockwise manner.

Soln: Let us first calculate the line integral along the given path



The work done will be

$$\begin{aligned} W &= \oint \mathbf{F} \cdot d\mathbf{r} = \int_{OA} \mathbf{F} \cdot d\mathbf{r} + \int_{AB} \mathbf{F} \cdot d\mathbf{r} + \int_{BC} \mathbf{F} \cdot d\mathbf{r} + \int_{CO} \mathbf{F} \cdot d\mathbf{r} \\ &= A(0) \int_0^a dx + 2A(a^2) \int_0^a dy + Aa^2 \int_a^0 dx + 2(0) \int_a^0 dy = 2Aa^3 \end{aligned}$$

To verify Stokes theorem we need to compute

$$\int (\nabla \times \mathbf{F}) \cdot d\mathbf{S}.$$

Here

$$\nabla \times \mathbf{F} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ Ay^2 & 2Ax^2 & 0 \end{vmatrix} = (4Ax - 2Ay)\hat{\mathbf{k}}$$

and

$$d\mathbf{S} = dx dy \hat{\mathbf{k}},$$

so that

$$\begin{aligned} \int (\nabla \times \mathbf{F}) \cdot d\mathbf{S} &= 4A \int_0^a x dx \int_0^a dy - 2A \int_0^a dx \int_0^a y dy \\ &= 4A\left(\frac{a^2}{2}\right)a - 2Aa\left(\frac{a^2}{2}\right) = 2Aa^3. \end{aligned}$$

Thus we get the same value of work done by computing the line integral, and by using the Stokes theorem.

5. Find the forces for the following potential energies

(a) $V(x, y, z) = Ax^2 + By^2 + Cz^2$

Soln:

$$\begin{aligned} \mathbf{F} &= -\nabla V = -\frac{\partial V}{\partial x}\hat{\mathbf{i}} - \frac{\partial V}{\partial y}\hat{\mathbf{j}} - \frac{\partial V}{\partial z}\hat{\mathbf{k}} \\ &= -2Ax\hat{\mathbf{i}} - 2By\hat{\mathbf{j}} - 2Cz\hat{\mathbf{k}} \end{aligned}$$

(b) $V(x, y, z) = A \ln(x^2 + y^2 + z^2)$

Soln:

$$\mathbf{F} = -\frac{\partial V}{\partial x} \hat{\mathbf{i}} - \frac{\partial V}{\partial y} \hat{\mathbf{j}} - \frac{\partial V}{\partial z} \hat{\mathbf{k}} = \frac{2A}{(x^2 + y^2 + z^2)} (x \hat{\mathbf{i}} + y \hat{\mathbf{j}} + z \hat{\mathbf{k}})$$

(c) $V(r, \theta) = A \cos \theta / r^2$ (r and θ are plane polar coordinates)

Above, A , B , and, C are constants.

Soln:

$$\begin{aligned} V &= \frac{A \cos \theta}{r^2} = \frac{Ax}{r^3} = \frac{Ax}{(x^2 + y^2)^{3/2}} \\ \implies \mathbf{F} &= -\frac{\partial V}{\partial x} \hat{\mathbf{i}} - \frac{\partial V}{\partial y} \hat{\mathbf{j}} = -A \left(\frac{1}{(x^2 + y^2)^{3/2}} - \frac{3x^2}{(x^2 + y^2)^{5/2}} \right) \hat{\mathbf{i}} + \frac{A3xy}{(x^2 + y^2)^{5/2}} \hat{\mathbf{j}} \\ &= \frac{A(2x^2 - y^2)}{(x^2 + y^2)^{5/2}} \hat{\mathbf{i}} + \frac{A3xy}{(x^2 + y^2)^{5/2}} \hat{\mathbf{j}} \end{aligned}$$

6. Determine whether each of the following forces is conservative. Find the potential energy function, if it exists. A , α , β are constants.

(a) $\mathbf{F} = A(3\hat{\mathbf{i}} + z\hat{\mathbf{j}} + y\hat{\mathbf{k}})$

Soln: First we compute the curl of \mathbf{F}

$$\nabla \times \mathbf{F} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 3A & Az & Ay \end{vmatrix} = 0.$$

Therefore, the force is conservative and it is possible to obtain a potential energy function for it using

$$\begin{aligned} -\frac{\partial V}{\partial x} &= 3A \\ -\frac{\partial V}{\partial y} &= Az \\ -\frac{\partial V}{\partial z} &= Ay. \end{aligned}$$

On integrating the first equation above we have

$$V(x, y, z) = -3Ax + f(y, z),$$

which on substitution in the second equation yields

$$\begin{aligned} -\frac{\partial f}{\partial y} &= Az \\ \implies f(y, z) &= -Ayz + C \\ \implies V(x, y, z) &= -3Ax - Ayz + C, \end{aligned}$$

where C is a constant. Note that this expression for V satisfies the third equation above, implying that the solution is complete.

(b) $\mathbf{F} = Axyz(\hat{\mathbf{i}} + \hat{\mathbf{j}} + \hat{\mathbf{k}})$

Soln:

$$\nabla \times \mathbf{F} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ Axyz & Axyz & Axyz \end{vmatrix} = A(xz - xy)\hat{\mathbf{i}} + A(xy - yz)\hat{\mathbf{j}} + A(yz - xz)\hat{\mathbf{k}} \neq 0,$$

therefore, a potential energy function does not exist for this force.

(c) $F_x = A \sin(\alpha y) \cos(\beta z)$, $F_y = -Ax\alpha \cos(\alpha y) \cos(\beta z)$, $F_z = Ax \sin(\alpha y) \sin(\beta z)$

Soln:

$$\begin{aligned} \nabla \times \mathbf{F} &= \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A \sin(\alpha y) \cos(\beta z) & -Ax\alpha \cos(\alpha y) \cos(\beta z) & Ax \sin(\alpha y) \sin(\beta z) \end{vmatrix} \\ &= A(x\alpha \cos(\alpha y) \sin(\beta z) - x\alpha\beta \cos(\alpha y) \sin(\beta z))\hat{\mathbf{i}} \\ &\quad + A(-x\beta \sin(\alpha y) \sin(\beta z) - x\alpha \cos(\alpha y) \sin(\beta z))\hat{\mathbf{j}} \\ &\quad + A(0 - \alpha \cos(\alpha y) \cos(\beta z))\hat{\mathbf{k}} \\ &\neq 0, \end{aligned}$$

hence, for this force also, no potential energy function exists.