

Newtonian mechanics & electrodynamics were established nicely but some problems came:

(1) \vec{E} & \vec{B} depending on frame (if \vec{v}_{rel} is diff, \vec{B} is diff.)

(2) $\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$ is not consistent in diff frames.

(3) speed of light $c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$ comes out to be constant (independent of frame?!)

so lol, Newtonian relativity & Galilean transformations do not apply to electrodynamics

→ it is not right, so we had to find a new theory.

* ether was the ref. frame where v_{light} came out to be $= c$

• so, what was wrong? EM? NM? RR? GT?

Einstein correctly showed that it was

NM + GT

Einstein's postulates:

- ① Principle of relativity (all frames are ~~equal~~ equivalent)
- ② Speed of light in free space is same in all ref. frames

(→ instead of proving this, he chose this as a postulate

step 1: make new transformation laws

& beat Newton

↳ (Lorentz transformation)

* Read up some more about inertial ref. frames.

• An implicit assumption in Einstein's postulates is that space & time are homogeneous

(space (length) intervals & time intervals are same always ~~of~~ anywhere (not frame to frame, anywhere within space of that frame)

Let's derive the Lorentz transformations:

relate (x, y, z, t)

(x', y', z', t')

using the fact that space & time are homogeneous

we can deduce that the $Ms.$ must be

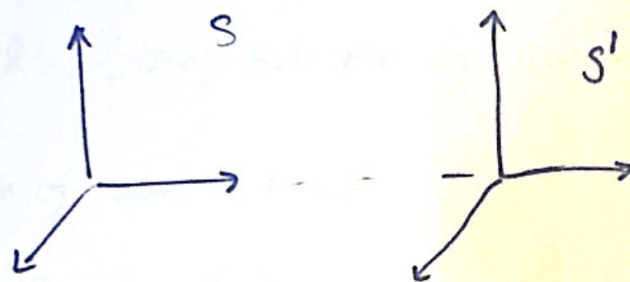
linear.

$$x' = a_{11}x + a_{12}y + a_{13}z + a_{14}t$$

$$y' = a_{21}x + a_{22}y + a_{23}z + a_{24}t$$

$$z' = a_{31}x + a_{32}y + a_{33}z + a_{34}t$$

$$t' = a_{41}x + a_{42}y + a_{43}z + a_{44}t$$



x axis coincides w/ x' axis

if $y \& z = 0$

$\Rightarrow y' \& z' = 0$

$\Rightarrow y' \& z'$ depend on $y \& z$ only

(because $x \& t$ are independent vars which cant make $y' \& z' = 0$)

w/ similar logic about xy & $x'y'$ plane

we simplify further:

now,

$$x' = a_{11}x + a_{12}y + a_{13}z + a_{14}t$$

$$y' = a_{22}y$$

$$z' = a_{33}z$$

$$t' = a_{41}x + a_{42}y + a_{43}z + a_{44}t$$

* Using P.R. (only rel. motion matters)

(i) length of unit rod in S

is a_{22} in S'

(ii) length of unit rod in S'

is $\frac{1}{a_{22}}$ in S

but these must be same cos all frames are equivalent

$$\Rightarrow \frac{1}{a_{22}} = a_{22}$$

$$\Rightarrow a_{22} = 1$$

a_{22} can't be -1 because it flips orientation

but all frames are equivalent & orientation must also be invariant on changing frames.

now,

$$x' = a_{11}x + a_{12}y + a_{13}z + a_{14}t$$

$$y' = y$$

$$z' = z$$

$$t' = a_{41}x + a_{42}y + a_{43}z + a_{44}t$$

* t is independent of y & z

$+y$ & $-y$ both give same t & z
 $+z$ & $-z$

\therefore they don't affect t or z
same for x

$$x' = a_{11}x + a_{14}t$$

$$y' = y$$

$$z' = z$$

$$t' = a_{41}x + a_{44}t$$

~~but we want~~

~~we want~~

$$x' = a_{11}(x - vt)$$

because $x' = 0$

always means

$$x = vt$$

when the frames start moving:

let a light bulb flash from the origin

& an EM pulse is emitted

• write their eqns:

$$x^2 + y^2 + z^2 = c^2 t^2$$

$$x'^2 + y'^2 + z'^2 = c^2 t'^2$$



$$a_{11}^2 (x - vt)^2 + y^2 + z^2 = c^2 (a_{41}x + a_{44}t)^2$$

$$a_{11}^2 (x^2 + v^2 t^2 - 2xvt) + y^2 + z^2 = c^2 (a_{41}^2 x^2 + a_{44}^2 t^2$$

$$+ 2a_{41}a_{44}xt)$$

$$a_{11}^2 - c^2 a_{41}^2 = 1 \quad - \quad (x^2 \text{ coeff})$$

$$c^2 a_{44}^2 - a_{11}^2 v^2 = c^2 \quad - \quad (t^2 \text{ coeff})$$

$$- a_{11}^2 2xv = c^2 2a_{41}a_{44} \quad - \quad (xt \text{ coeff})$$

$$a_{11}^2 = 1 + c^2 a_{41}^2$$

$$a_{11}^2 = \frac{c^2 (a_{44}^2 - 1)}{v^2}$$

$$a_{11}^2 = \frac{-c^2 a_{41} a_{44}}{v}$$

on solving:

$$a_{44} = \frac{1}{\sqrt{1 - v^2/c^2}}$$

$$a_{11} = \frac{1}{\sqrt{1 - v^2/c^2}}$$

$$a_{41} = \frac{-v}{c} \frac{1}{\sqrt{1 - v^2/c^2}}$$

\therefore Lorentz transformation comes as:

$$x' = \frac{x - vt}{\sqrt{1 - v^2/c^2}}$$

$$y' = y$$

$$z' = z$$

$$t' = \frac{t - \frac{v}{c^2}x}{\sqrt{1 - v^2/c^2}}$$

* we use some notations:

$$\frac{v^2}{c^2} = \beta^2$$

$$\frac{1}{\sqrt{1 - v^2/c^2}} = \gamma$$

Some consequences of this:

- ① Time dilation
- ② Length contraction
- ③ Synchronization & simultaneity

Let's examine ②:

A rod has rest length $x_2 - x_1$ in S' frame (moving)

$$x_2' = \frac{x_2 - vt_2}{\sqrt{1 - \beta^2}}$$

$$x_1' = \frac{x_1 - vt_1}{\sqrt{1 - \beta^2}}$$

$$x_2' - x_1' = \frac{(x_2 - x_1) - v(t_2 - t_1)}{\sqrt{1 - \beta^2}}$$

* t_2 has to be = t_1 for length to be measured in a moving frame (simultaneity) $\Rightarrow x_2' - x_1' = \frac{x_2 - x_1}{\sqrt{1 - \beta^2}}$

$$\Rightarrow \Delta l = \sqrt{1 - \beta^2} \Delta l'$$

↓
less than 1

so we observe a contracted length.

* any length \perp to the motion is unaffected.

* now lets see time dilation :

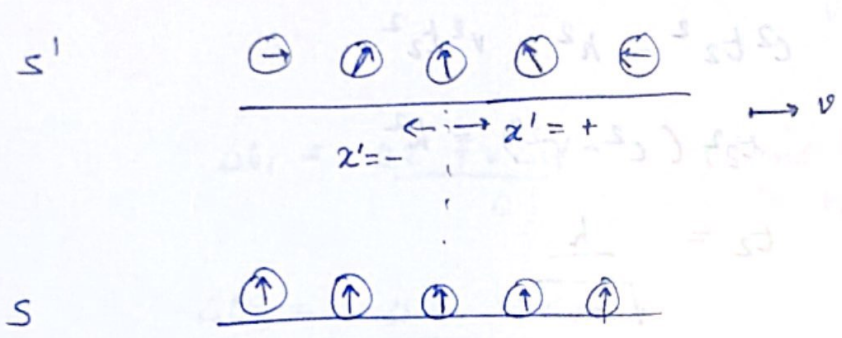
$$t = \frac{t' + \frac{v}{c^2} x'}{\sqrt{1 - v^2/c^2}} \quad \text{— why?}$$

bec. $v_{rel} = -v$
on switching frames

$$t_2 - t_1 = \frac{t_2' - t_1' + \frac{v}{c^2} (x_2' - x_1')}{\sqrt{1 - v^2/c^2}} \quad \text{— why?}$$

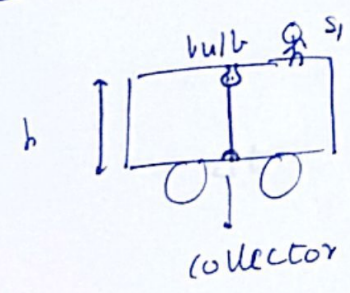
$$\Delta t = \frac{\Delta t'}{\sqrt{1 - v^2/c^2}}$$

③ simultaneity & synchronisation



when $x' = +ve$ because $t = \text{const.}$
 $t' = -ve$ (synchronised clocks in S)
 $x' = -ve$
 $t' = +ve$
 so stuff changes in S'

Time dilation expt.:



$t_1 = \frac{h}{c}$

for t_2 : path of light is

$t_2 = \frac{\sqrt{h^2 + v^2 t_2^2}}{c}$
 not $\sqrt{c^2 + v^2}$ (acc. to Galileo)

$$\Rightarrow t_2 = \frac{\sqrt{h^2 + v^2 t_2^2}}{c}$$

$$c^2 t_2^2 = h^2 + v^2 t_2^2$$

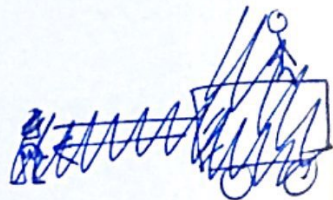
$$t_2^2 (c^2 - v^2) = h^2$$

$$t_2 = \frac{h}{\sqrt{c^2 - v^2}}$$

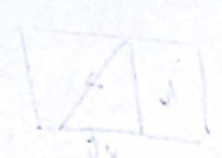
$$= \frac{h}{c} \cdot \frac{1}{\sqrt{1 - v^2/c^2}}$$

time = $t_1 \cdot \frac{1}{\sqrt{1 - v^2/c^2}}$

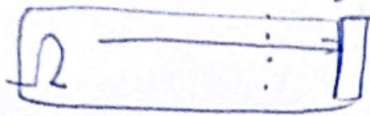
length contraction eqn:



$$\Delta t' = \frac{2 \Delta x'}{c}$$



while going, the front moved ahead by $v\Delta t_1$



while coming back, the back moved ahead by $v\Delta t_2$

$$\Delta t_1 = \frac{\Delta x + v\Delta t_1}{c} \quad (\text{time taken to hit cart.})$$

$$\Delta t_2 = \frac{\Delta x - v\Delta t_2}{c}$$

$$\Rightarrow \Delta t_1 \left(1 - \frac{v}{c}\right) = \frac{\Delta x}{c}$$

$$\Delta t_1 = \frac{\Delta x/c}{1 - v/c}$$

$$\rightarrow \Delta t_2 = \frac{\Delta x/c}{1 + v/c}$$

$$\Delta t = \Delta t_1 + \Delta t_2$$

$$= \frac{\Delta x}{c} \left(\frac{2}{1 - v^2/c^2} \right)$$

$$\Delta t = \frac{2\Delta x}{c} \frac{1}{1 - v^2/c^2}$$

~~the time taken~~

time taken for the front

$$\frac{\Delta t'}{\sqrt{1 - v^2/c^2}} = \frac{2\Delta x}{c} \frac{1}{1 - v^2/c^2}$$

$$\frac{2\Delta x/c}{\sqrt{1 - v^2/c^2}} = \frac{2\Delta x}{c} \frac{1}{1 - v^2/c^2}$$

$$\Delta x' = \frac{\Delta x}{\sqrt{1 - v^2/c^2}}$$

Finding out velocity:

$$x' = \frac{x - vt}{\sqrt{1 - v^2/c^2}}$$

$$t' = \frac{t - \frac{v}{c^2}x}{\sqrt{1 - v^2/c^2}}$$

$$\Delta x' = \frac{\Delta x - v\Delta t}{\sqrt{1 - v^2/c^2}}$$

$$\Delta t' = \frac{\Delta t - \frac{v}{c^2}\Delta x}{\sqrt{1 - v^2/c^2}}$$

$$u_x' = \frac{\Delta x'}{\Delta t'} = \frac{\Delta x - v\Delta t}{\Delta t - \frac{v}{c^2}\Delta x}$$

$$= \frac{\Delta x - v\Delta t}{\Delta t - \frac{v}{c^2}\Delta x}$$

$$= \frac{\Delta x/\Delta t - v}{1 - \frac{v}{c^2} \frac{\Delta x}{\Delta t}}$$

$$= \frac{u_x - v}{1 - \frac{u_x v}{c^2}}$$

$v \rightarrow$ vel. of the frame

$u_x', u_x \rightarrow$ vel. of sm that is moving

$$u_x = \frac{u_x' + v}{1 + \frac{u_x' v}{c^2}}$$

put $u_x' = c$

check u_x

$$u_x = \frac{c + v}{1 + \frac{cv}{c^2}} = \frac{c + v}{1 + \frac{v}{c}} = c \quad \checkmark$$

satisfies
Einstein's
postulate

for u_y :

$$\Delta y' = \Delta y$$

$$\Delta t' = \frac{\Delta t - \frac{v}{c^2} \Delta x}{\sqrt{1 - v^2/c^2}}$$

$$u_y' = \frac{\Delta y'}{\Delta t'} = \frac{\Delta y}{\Delta t - \frac{v}{c^2} \Delta x} \sqrt{1 - v^2/c^2}$$

$$= \frac{1}{\gamma} \frac{u_y}{1 - \frac{v}{c^2} u_x} \neq$$

$$u_y' = u_y \cdot \left(\frac{1}{1 - \frac{v}{c^2} u_x} \right) \frac{1}{\gamma}$$

$$\gamma = \frac{1}{\sqrt{1 - v^2/c^2}}$$

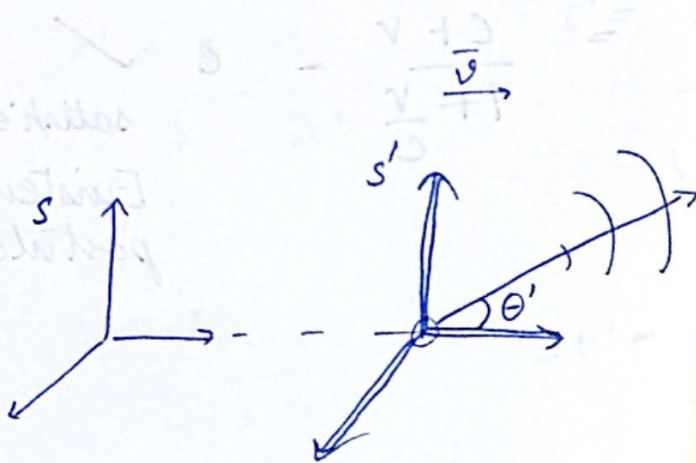
exclusive
Relativistic effect

y velocity getting
affected by x motion.

Doing same math:

$$a_{x'} = \frac{a_x \cdot (1 - v^2/c^2)^{3/2}}{\left(1 - \frac{u_x v}{c^2}\right)^3}$$

Doppler effect & aberration:



wave: $\cos 2\pi \left[\frac{x' \cos \theta' + y' \sin \theta' - v't'}{\lambda'} \right] \quad (1)$

v nu
(freq.)

relate w/

$$\cos 2\pi \left[\frac{x \cos \theta + y \sin \theta - vt}{\lambda} \right] \quad (2)$$

* constraint: $c = v' \lambda' = v \lambda$

use L.T & sub. x' & t' using x, t
 and you get (1) in terms of the vars. of

(2) ...

(1) :

$$\cos 2\pi \left[\frac{x}{\lambda} (x-vt) \omega \theta' + \frac{y \sin \theta' - v' \gamma (1 - \frac{v}{c^2} x)}{\lambda'} \right]$$

(...)

$$\cos 2\pi \left[\left(\frac{\omega \theta' + \beta}{\lambda'} \right) \gamma x + \frac{\sin \theta' y}{\lambda'} - \gamma (\beta \omega \theta' + 1) v' t \right]$$

* $\beta = v/c$
 $\gamma = \frac{1}{\sqrt{1-v^2/c^2}}$ \Rightarrow compare w/ (2)

$$\Rightarrow \left. \begin{aligned} \frac{\cos \theta}{\lambda} &= \left(\frac{\cos \theta' + \beta}{\lambda'} \right) \gamma \\ \frac{\sin \theta}{\lambda} &= \frac{\sin \theta'}{\lambda'} \end{aligned} \right\} \text{Aberration}$$

$$\nu = \nu' (1 + \beta \cos \theta') \gamma \quad \left. \vphantom{\frac{\cos \theta}{\lambda}} \right\} \text{Doppler effect}$$

* $\beta = v/c$... first order in v/c

$$\gamma = \frac{1}{\sqrt{1-\beta^2}} = (1-\beta^2)^{-1/2}$$

... second order in v/c

$$\approx 1 + \frac{1}{2}\beta^2$$
$$\approx 1 + \frac{1}{2} \cdot \frac{v^2}{c^2}$$

In order 1 in terms of β :

$O(\beta^1)$:

we have $v = v'(1 + \beta \cos \theta')$

useful if we have $v = v(v', \theta')$
not $f(v', \theta')$

so we do,

$$v' = v(1 - \beta \cos \theta) \gamma$$

$$\Rightarrow v = \frac{v'}{(1 - \beta \cos \theta) \gamma}$$

$$v = \frac{v' \sqrt{1-\beta^2}}{(1 - \beta \cos \theta)}$$

* special cases:

(i) $\theta = 0$

$$\Rightarrow \nu = \frac{\nu' \sqrt{1-\beta^2}}{1-\beta}$$

(ii) $\theta = \pi$

$$\Rightarrow \nu = \frac{\nu' \sqrt{1-\beta^2}}{1+\beta}$$

* Limiting approximations for classical mech:

$\beta \ll 1$

(i) $\nu = \nu' (1 + \beta)^{-1}$

$= \nu' (1 + \beta)$ → checks out!

(ii) $\nu = \nu' (1 - \beta)$

$O(\beta^2)$ terms are ignored to show C.M doppler effect. It comes in to show relativistic effects

coming to exact expressions:

$$\theta = 0 \rightarrow v = v' \sqrt{\frac{1+\beta}{1-\beta}}$$

$$\theta = \pi \rightarrow v = v' \sqrt{\frac{1-\beta}{1+\beta}}$$

put $\theta = \pi/2$

$$\Rightarrow v = v' \sqrt{1-\beta^2}$$

... the first term is

$\beta^2 \rightarrow$ not appearing in Newtonian mech.

purely relativistic effect.

Four-vectors:

$X \rightarrow$ our four vector

(ct, x, y, z)

$X^0 = ct$ (multiplied by c to make dim. same)

$X^1 = x$

$X^2 = y$

$X^3 = z$

$X^n \rightarrow n^{\text{th}}$ component not power

$X^1 \rightarrow$ another f.v in S^1

$$X^{0'} = \gamma (X^0 - \beta X^1)$$

$$X^{1'} = \gamma (X^1 - \beta X^0)$$

$$X^{2'} = X^2$$

$$X^{3'} = X^3$$

lets write in matrix form:

$$\begin{pmatrix} X^{0'} \\ X^{1'} \\ X^{2'} \\ X^{3'} \end{pmatrix} = \begin{pmatrix} \gamma & -\gamma\beta & 0 & 0 \\ -\gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} X^0 \\ X^1 \\ X^2 \\ X^3 \end{pmatrix}$$

$$X^{\mu'} = \sum_{\nu=0}^3 \Lambda_{\nu}^{\mu} X^{\nu}$$

(Expanded form of matrix multiplication)

$$X^{0'} = \sum_{\nu=0}^3 \Lambda_{\nu}^0 X^{\nu}$$

$$\Lambda_0^0 X^0 = \gamma \cdot X^0$$

$$+ \Lambda_1^0 X^1 = -\gamma\beta \cdot X^1$$

$$+ \Lambda_2^0 X^2 = 0$$

$$+ \Lambda_3^0 X^3 = 0$$

& so on.

* any object

$$a'^{\mu} = \sum_{\nu=0}^3 \Lambda^{\mu}_{\nu} a^{\nu}$$

which obeys this,

is a four vector.

constraint :

$$-c^2 t^2 + x^2 + y^2 + z^2 = -c^2 t'^2 + x'^2 + y'^2 + z'^2$$

↓
(length of four vector)

$$\hookrightarrow |\Delta s|^2 = -x_0^2 + x_1^2 + x_2^2 + x_3^2$$

$$\overline{A \cdot B} = \sum_1^3 A_i B_i$$

→ invariant on transforming

space (3D)

same for four vectors in 4D

$$a \cdot b = \sum_0^3 a^{\mu} b_{\mu} = -a^0 b^0 + a^1 b^1 + a^2 b^2 + a^3 b^3$$

→ invariant

$$|\Delta s|^2 = -c^2 \Delta t^2 + (\Delta d)^2$$

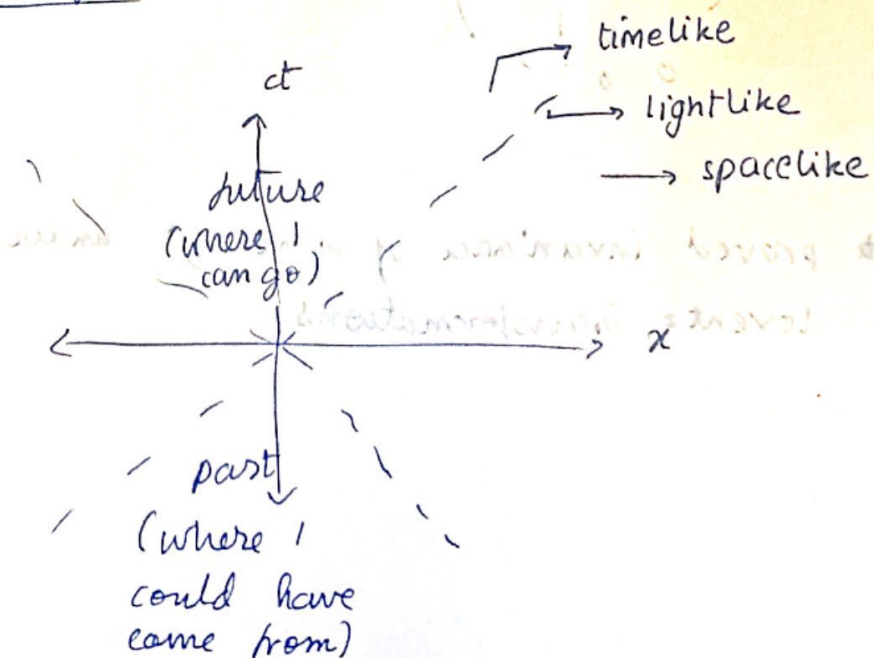
$|\Delta s|^2 > 0 \rightarrow$ spacelike

if two events are not simultaneous
i can change frame such
that they are ($\Delta t = 0$) but
i can never make $\Delta d = 0$
(make them happen at same
location)

$|\Delta s|^2 < 0 \rightarrow$ timelike
(vice versa)

$|\Delta s|^2 = 0 \rightarrow$ light like
(moves w/ speed of light)

Minkowski diagram:



* notation:

$$a_\mu = (a_0, a_1, a_2, a_3)$$

$$a^\mu = (-a_0, a_1, a_2, a_3)$$

covariant $\leftarrow a_\mu = (-a_0, a_1, a_2, a_3)$

contravariant $\leftarrow a^\mu = (a_0, a_1, a_2, a_3)$

$$a^\mu a_\mu = -a_0^2 + a_1^2 + a_2^2 + a_3^2$$

$$a_\mu = g_{\mu\nu} a^\nu$$

↓

$$\begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

* proved invariance of wave eqn under Lorentz transformations.

we have $s = \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix}$

$\Delta s = \begin{pmatrix} c\Delta t \\ \Delta x \\ \Delta y \\ \Delta z \end{pmatrix}$

lets get v :

we cant use $\frac{\Delta s}{\Delta t}$ because Δt is a changing parameter of Δs itself

we use Δt → proper time interval (measured when moving w/ same vel. as clock)

4-velocity (proper vel.) = $\begin{pmatrix} c \frac{dt}{d\tau} \\ \frac{dx}{d\tau} \\ \frac{dy}{d\tau} \\ \frac{dz}{d\tau} \end{pmatrix} = \gamma \begin{pmatrix} c \\ dx/dt \\ dy/dt \\ dz/dt \end{pmatrix}$

★ Quiz on 26th Aug.

(Syllabus is whatever done till 19th Aug.)

$$\underline{s} = (ct, \vec{r})$$

$$d\underline{s} = (cdt, d\vec{r})$$

$$\underline{u} = \frac{d\underline{s}}{dt} = \left(\frac{cdt}{dt}, \frac{d\vec{r}}{dt} \right)$$

$$= \gamma (c, \vec{v})$$

★ \underline{u} follows transformation law: $\underline{u}'^M = \Lambda^M_{\ \gamma} \underline{u}^\gamma$

★ Try finding rel. v. formula using four velocity formalism.

Let's define momentum:

$$\underline{p} = m_0 \underline{u}$$

$$= m_0 (rc, r\vec{u}) = (m_0 c, m_0 \vec{u}) \rightarrow \frac{d\vec{y}}{dt} \text{ not } \frac{d\vec{r}}{dt}$$

$$= m_0 \gamma (c, \vec{v})$$

where $m = \gamma m_0$

$$= (mc, \vec{p})$$

$m \rightarrow$ frame dependent

$$m = \gamma m_0$$

\hookrightarrow Rest mass

\hookrightarrow Relativistic mass

$\vec{p} \rightarrow$ spatial comp. of momentum four vector

$$= m \vec{u}$$
$$= \gamma m_0 \cdot \frac{d\vec{x}}{dt}$$

The time component of four vector p

$$= (mc) \text{ and that is } = \frac{E}{c}$$

... we'll show why.

• what is force?

$$\begin{aligned} \text{Minkowski force} \quad \underline{F} &= \frac{dp}{d\tau} \\ &= \left(\frac{d}{dt}(mc), \frac{d}{dt}(\vec{p}) \right) \\ &= \gamma \left(\frac{d(mc)}{dt}, \frac{d\vec{p}}{dt} \right) \\ &= \gamma \left(\frac{d(mc)}{dt}, \vec{F} \right) \end{aligned}$$

* here we don't absorb γ into the spatial comp. like we did for momentum bc that def. of \underline{p} helps us maintain momentum conservation.

★ In 3D:

$$\underline{F} \cdot \underline{u} = \frac{dE}{dt}$$

lets try sm similar here

$$\underline{F} \cdot \underline{u} = F^\mu u_\mu$$

$$= \gamma \left(\frac{d(mc)}{dt}, \underline{F} \right) \cdot \gamma (c, \underline{u})_\mu$$

$$= \gamma^2 \left(\underline{F} \cdot \underline{u} - c \frac{d(mc)}{dt} \right)$$

$$= \gamma^2 \left(\underline{F} \cdot \underline{u} - \frac{d}{dt} (mc^2) \right)$$

now work this ...

★ This dot product $\underline{F} \cdot \underline{u}$ is invariant of frame.

lets examine it in the rest frame,

$$\text{where } \underline{u} = (0, \frac{h}{Jh}, (3m) \frac{h}{Jh})$$

$$\Rightarrow \underline{F} \cdot \underline{u} = 0$$

check the other term:

$$\frac{d}{dt} (mc^2) \Big|_{\underline{u}=0}$$

$$= \frac{d}{dt} \left(\frac{m_0 c^2}{\sqrt{1 - \frac{u^2}{c^2}}} \right) \Big|_{\underline{u}=0}$$

$$= m_0 c^2 \left(-\frac{1}{2}\right) \frac{1}{(1 - u^2/c^2)^{3/2}} \cdot -2u \frac{du}{dt}$$

$$= \frac{m_0 c^2 \cdot u \cdot \frac{du}{dt}}{(1 - u^2/c^2)^{3/2}} \Big|_{\bar{u}=0}$$

$$= 0$$

∴ They are both zero here and $\underline{F} \cdot \underline{u} = 0$ in this frame.

If you go to another frame: $\underline{F} \cdot \underline{u} = 0$

Summary

$\underline{F} \cdot \underline{u}$ might change

$\frac{d}{dt}(mc^2)$ might change

but $\underline{F} \cdot \underline{u} = 0$ will always hold

bec. dot product is frame invariant.

$$\Rightarrow \underline{F} \cdot \underline{u} = \frac{d}{dt}(mc^2) \quad (\text{in all frames})$$

$$\int \frac{dE}{dt} = \int \frac{d}{dt}(mc^2)$$

$$\Rightarrow E = mc^2$$

★ Read R, G for the other method

now, clearly:

$$\underline{p} = \left(\frac{E}{c}, \vec{p} \right)$$

Energy momentum
vector!

$$\underline{p}^M \cdot \underline{p}_M = \left(\frac{E}{c}, \vec{p} \right)^M \left(\frac{E}{c}, \vec{p} \right)_M$$

$$\downarrow = |\vec{p}|^2 - \frac{E^2}{c^2}$$

an invariant

↳ in a rest frame

$$|\vec{p}| = 0$$

$$= -\frac{E^2}{c^2} = -m^2 c^2 = \boxed{-m_0^2 c^2}$$

↓ invariant

$$|\vec{p}|^2 - \frac{E^2}{c^2} = -m_0^2 c^2$$

$$\Rightarrow \boxed{E^2 = |\vec{p}|^2 c^2 + m_0^2 c^4}$$

total
energy

corr
to KE

corr
to rest
mass energy

$E - mc^2 \approx KE$ (so it should corr. to Newtonian mechanics)

$$= mc^2 - mc^2$$

$$= \gamma mc^2 - mc^2$$

$$= mc^2 (\gamma - 1)$$

$$= mc^2 \left(\frac{1}{\sqrt{1 - \frac{u^2}{c^2}}} - 1 \right)$$

$$= mc^2 \left(1 + \frac{1}{2} \frac{u^2}{c^2} - 1 \right)$$

$$= \frac{1}{2} mu^2 \dots \text{checks out!}$$

Summary:

$$E = mc^2 = \gamma mc^2$$

$$E^2 = |\vec{p}|^2 c^2 + m_0^2 c^4$$

$$KE = E - mc^2$$

* A particle w/o mass can still have mechanics

(non zero energy $E = pc$)

but they will have to travel at speed of light.

because $\vec{p} = m_0 \gamma \vec{u}$

$$= \frac{m_0}{\sqrt{1 - \frac{u^2}{c^2}}} \vec{u}$$

should also be 0 to cause indeterminacy so that \vec{p} is finite

Revisiting Newton's Laws:

① First law - checks out

(read kleppner

Kolenkow

first chap)

② Second law -

$$\vec{F} = \frac{d\vec{p}}{dt}$$

→ Newton: $\vec{p} = m\vec{u}$

→ Einstein: $\vec{p} = m\vec{u}$

$$= \gamma m_0 \vec{u}$$

here,

$$\vec{F} = \frac{d}{dt}(m_0 \gamma u) = m_0 \frac{d(\gamma u)}{dt}$$

→ both have

time dependence

$$= m_0 \left[\gamma \frac{du}{dt} + u \frac{d\gamma}{dt} \right]$$

→ additional term to the usual acc. dependence.

$$\vec{F} = \frac{\vec{F} \cdot \vec{u}}{c^2} \vec{u} + m_0 \vec{a}$$

* you need nonzero \vec{a} for nonzero \vec{F}

but

$\vec{F} \parallel \vec{a}$ is not necessarily true!

$$\gamma = \frac{1}{\sqrt{1-u^2/c^2}}$$

$$\frac{d\gamma}{dt} = \frac{1}{\sqrt{1-u^2/c^2}}^{-3/2} \cdot \frac{-2u}{c^2} \frac{du}{dt}$$

$$= \frac{u \cdot \vec{a}}{(1-u^2/c^2)^{3/2}}$$

$$m_0 \vec{u} \frac{d\gamma}{dt} = \vec{u} \left(\frac{m_0 \cdot u \cdot a}{(1-u^2/c^2)^{3/2}} \right) \rightarrow \vec{F} \cdot \vec{u}$$

③ Action-reaction pair -

Newton: $F_{AB}(t) = -F_{BA}(t)$

↳ forces are equal at the same instant

but in general, there is a time delay for the reaction force to come

This still works if it is a contact force (no dist in $x \Rightarrow t = t'$)
OR if there is no time dependence of force

So, it may or may not hold.
(Frame dependent)

⇒ It is not true anymore because a law cannot be frame dependent.

Summary of new mechanics (consistent w/ Lorentz transformation)

$$\bar{u} = \frac{d\bar{x}}{dt}$$

$$\bar{p} = m\bar{u} = \gamma m_0 \bar{u}$$

$$\bar{F} = \frac{d\bar{p}}{dt}$$

$$E = mc^2 = \sqrt{|\bar{p}|^2 c^2 + m_0^2 c^4}$$

$$KE = (\gamma - 1) m_0 c^2$$

Real physical observables in 3-space

4-space

$$\underline{\Delta} = (ct, \bar{x})$$

$$\underline{u} = (\gamma c, \gamma \bar{u})$$

$$\underline{p} = (mc, \bar{p}) = \left(\frac{E}{c}, \bar{p}\right)$$

$$\underline{F} = \gamma \left(\frac{d}{dt}(mc), \bar{F}\right)$$

- This stuff helps us formulate relativistic definitions.
- New physical insight about spacetime structure.
- Easy to change frames (because of four vectors formalism)

$$Q'^M = \Lambda^M_{\ Y} Q^Y$$

$Q', Q \rightarrow$ some quantity in diff. frames

- Norms & dot products are invariant under transformation.

Some applications of new dynamics:

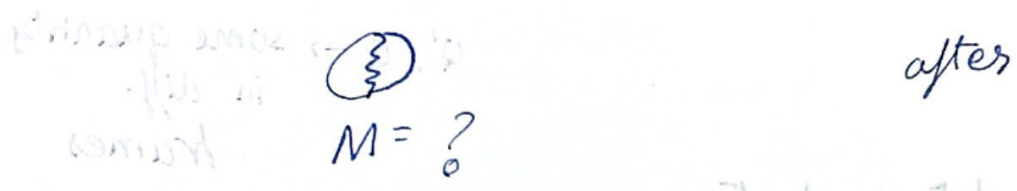
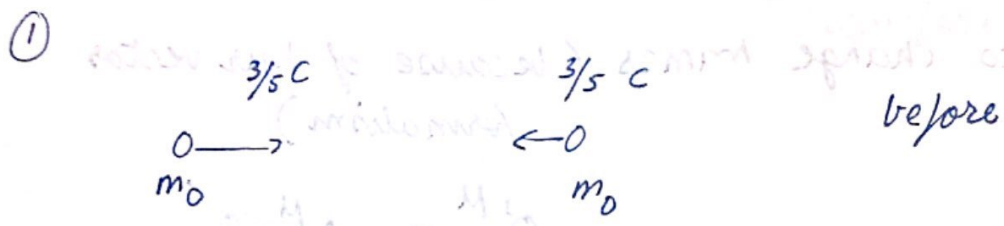
- (A) $L \rightarrow \bar{F} = 0 \Rightarrow$ conservation of momentum & energy
- (B) $L \rightarrow \bar{F} \neq 0 \Rightarrow$ trajectories of particles

* in relativistic mech, there is no concept of elastic & inelastic collision \Rightarrow if momentum is conserved, total energy also must be conserved.

Examples:

- (1) Inelastic $\rightarrow \begin{matrix} 0+0 \rightarrow 0 \\ 0 \rightarrow 0+0 \end{matrix} \left. \vphantom{\begin{matrix} 0+0 \rightarrow 0 \\ 0 \rightarrow 0+0 \end{matrix}} \right\} \text{(A)}$
- (2) Elastic $\rightarrow 0+0 \rightarrow 0+0$
- (3) constant force $\left. \vphantom{0+0 \rightarrow 0+0} \right\} \text{(B)}$

(A) Inelastic collision \rightarrow KE totally lost
 total E conserved



\rightarrow clearly $P_{net} = 0$ and $P_M = 0$

$$E_1 = \frac{\gamma m_0 c^2}{\sqrt{1 - 3/5^2}} = \frac{5}{4} m_0 c^2$$

$$E_2 = E_1 = \frac{5}{4} m_0 c^2$$

$$E_{tot} = E_1 + E_2$$

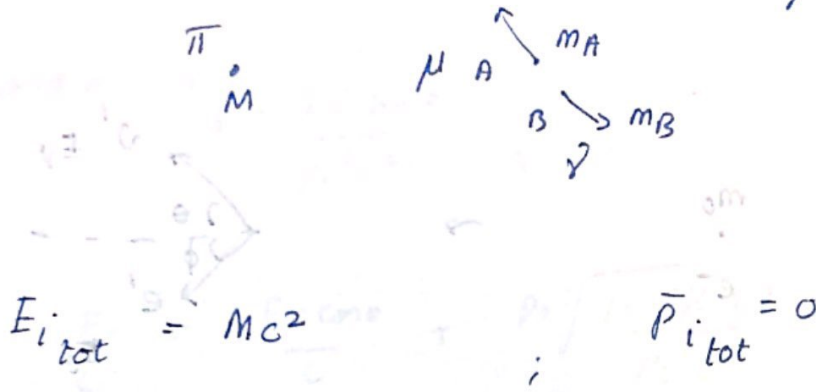
$$= \frac{5}{2} m_0 c^2 = M c^2$$

$$M = \frac{5}{2} m_0 > 2 m_0$$

Final rest mass $>$ sum of initial rest masses

(2) disintegration

π - pion
 μ - muon
 ν - neutrino



$$E_{f\text{ tot}} = E_{fA} + E_{fB} \quad \vec{P}_{f\text{ tot}} = \vec{P}_{fA} + \vec{P}_{fB}$$

$$E_{fA} = \sqrt{P_A^2 c^2 + m_A^2 c^4}$$

$$E_{\text{tot}} = E_{fA} + \sqrt{P_B^2 c^2 + m_B^2 c^4} = Mc^2$$

$$E_{fA} + \sqrt{P_A^2 c^2 + m_B^2 c^4} = Mc^2$$

$$E_{fA} + \sqrt{E_{fA}^2 - m_A^2 c^4 + m_B^2 c^4} = Mc^2$$

→ only one unknown E_{fA}
 so solve

$$\Rightarrow E_{fA} = \frac{c^2 (M^2 + m_A^2 - m_B^2)}{2M}$$

Elastic collision:



Kind relation of E_γ with θ

$$E_{\gamma i} + E_{e i} = E_{\gamma f} + E_{e f} \quad \dots \text{Energy cons.}$$

$$E_0 + m_0 c^2 = E_\gamma + E_e = E_\gamma + \sqrt{p_e^2 c^2 + m_0^2 c^4} \quad \text{--- (1)}$$

vertical momentum conservation :

$$p_e \sin \phi = p_\gamma \sin \theta$$

$$= \frac{E_\gamma}{c} \sin \theta$$

horizontal :

$$\frac{E_0}{c} + 0 = p_\gamma \cos \theta + p_e \cos \phi$$

$$\sin \phi = \frac{E_r \sin \theta}{P_e c}$$

$$\cos \phi = \sqrt{1 - \frac{E_r^2 \sin^2 \theta}{P_e^2 c^2}}$$

$$\Rightarrow \frac{E_0}{c} = \frac{E_r \cos \theta}{c} + P_e \sqrt{1 - \frac{E_r^2 \sin^2 \theta}{P_e^2 c^2}}$$

$$\Rightarrow \boxed{E_r = \frac{E_0}{1 + \frac{E_0}{m_0 c^2} (1 - \cos \theta)}}$$

$$\boxed{\lambda = \lambda_0 + \lambda_c (1 - \cos \theta)}$$

$$\lambda_c = \frac{h}{m_0 c}$$

... Compton scattering

Trajectories:

$\bar{F} = \text{constant.}$

Newtonian: $\Delta x = ut + \frac{1}{2} at^2$; $\frac{F}{m} = a$

$$x = \frac{1}{2} at^2$$



Relativistically:

$$\frac{dp}{dt} = F$$

$$= \text{constant } F$$

$$p = \gamma m_0 u$$

$$\Rightarrow p = \frac{Ft + c}{\sqrt{1 - \frac{u^2}{c^2}}}$$

$$\frac{m_0 u}{\sqrt{1 - \frac{u^2}{c^2}}} = Ft$$

solve for u

$$m_0^2 u^2 = F^2 t^2 - \frac{F^2 t^2 u^2}{c^2 - 1}$$

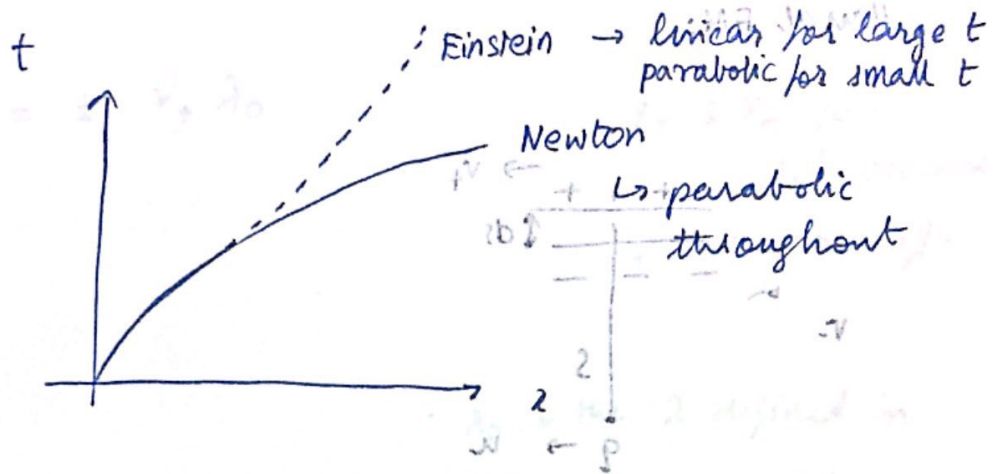
$$u^2 \left[m_0^2 + \frac{F^2 t^2}{c^2} \right] = F^2 t^2$$

$$u = \frac{Ft}{\sqrt{m_0^2 + \frac{F^2 t^2}{c^2}}} = \frac{\frac{F}{m_0} t}{\sqrt{1 + \left(\frac{Ft}{m_0 c}\right)^2}}$$

$$\frac{dx}{dt} = \frac{\frac{F}{m_0} t}{\sqrt{1 + \left(\frac{Ft}{m_0 c}\right)^2}}$$

$$x = \int_0^t \frac{\frac{F}{m_0} t'}{\sqrt{1 + \left(\frac{Ft'}{m_0 c}\right)^2}} dt'$$

$$\Rightarrow x(t) = \frac{m_0 c^2}{F} \left[\sqrt{1 + \left(\frac{Ft}{m_0 c}\right)^2} - 1 \right]$$



$x(t)$ for small t

$$= \frac{m_0 c^2}{F} \left(1 + \frac{1}{2} \frac{F^2 t^2}{m_0^2 c^2} - 1 \right)$$

$$= \left(\frac{1}{2} \right) \frac{F}{m_0} t^2$$

$x \propto t^2$

for large t :

$$\left(\frac{Ft}{m_0 c}\right)^2 \gg 1$$

$$\Rightarrow x(t) = \frac{m_0 c^2}{F} \left[\frac{Ft}{m_0 c} - 1 \right]$$

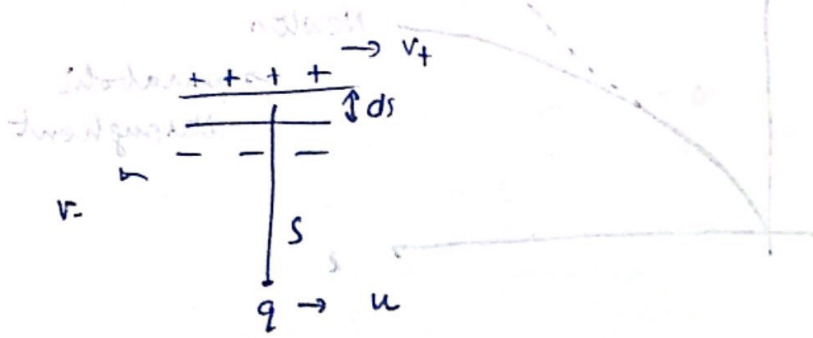
$$x \propto t$$

Newtonian mechanics at low speeds only

$$\frac{p}{\hbar} \pm \frac{p}{\hbar} = \pm \frac{p}{\hbar}$$

Relativistic electrodynamics:

Unal EM: ...
 ...



\vec{E} \vec{B} \vec{F}

0 $\left(1 - \frac{v^2}{c^2}\right)^{-1/2}$ $q \cdot u = \frac{\mu_0 I}{2\pi s}$; $I = 2\lambda v$

(-into paper) \rightarrow (up)

now, sit in q frame:

transform velocities of these charges:

$$\left[1 - \frac{v^2}{c^2}\right]^{-1/2} = \frac{v_{\vec{F}} u}{1 + \frac{uv}{c^2}}$$

λ will also change due to length contraction

$$\lambda_{\pm} = \pm \frac{Q}{L_{\pm}} = \pm \frac{Q}{L_0 \gamma_{\pm}} \quad \text{L}_0 - \text{proper length}$$

$$\lambda_{\pm} = \pm \frac{Q}{L_0} \sqrt{1 - \frac{v_{\pm}^2}{c^2}}$$

λ_0 - proper charge density

$$= \pm \gamma_{\pm} \lambda_0$$

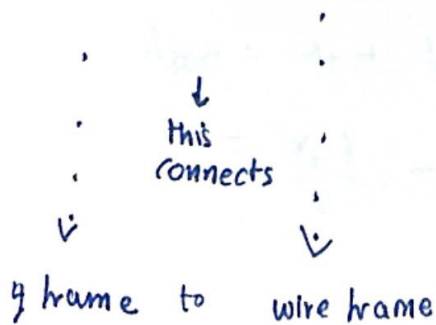
γ_+ & γ_- are diff because

v_+ & v_- are diff.

- λ_0 & the λ defined in lab frame are diff.
- λ_0 is measured in a frame where charges are at rest
- λ " in lab frame, where charges are moving w/ v_+ & v_-

• λ_{\pm} is measured in q-frame

$$\lambda_{\pm} = \pm \gamma_{\pm} \lambda_0$$



• We want to connect q frame to lab frame

$$\therefore \pm \lambda = \pm \gamma \lambda_0$$

lab
frame

$$\gamma = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$v = \frac{v_+}{v_-}$$

$$\Rightarrow \lambda_{\pm} = \pm \gamma_{\pm} \left(\frac{\lambda}{\gamma} \right)$$

$$\lambda_{\pm} = \pm \left(\frac{\gamma_{\pm}}{\gamma} \right) \lambda$$

g
frame

lab
frame

$\gamma_{\pm} \rightarrow v_+ \& v_-$
in g frame
($v_+ \& v_-$)

γ - with original
(v)

let's recalculate!

* lab frame :

$$\lambda_{\text{tot}} = 0 \Rightarrow \bar{E} = 0$$

* g frame :

$$\lambda_{\text{tot}} = \lambda_+ + \lambda_-$$

$$= \frac{\gamma_+ \lambda}{\gamma} - \frac{\gamma_- \lambda}{\gamma}$$

$$= \frac{\lambda}{\gamma} (\gamma_+ - \gamma_-)$$

Simplify γ_{\pm} : you get :

$$\gamma_{\pm} = \gamma \frac{1 \mp \frac{uv}{c^2}}{\sqrt{1 - \frac{u^2}{c^2}}}$$

$$\frac{\gamma_+ - \gamma_-}{\gamma} = \frac{-2uv}{c^2 \sqrt{1 - \frac{u^2}{c^2}}}$$

$$\therefore \lambda_{tot} = \frac{-2\lambda uv}{c^2 \sqrt{1 - \frac{u^2}{c^2}}}$$

$$\bar{E} = \frac{\lambda_{tot}}{2\pi\epsilon_0 \cdot s}$$

* s is not contracted
bc its \perp to vel.

* There is a modified \bar{B} as well,
due to diff λ, v

but since in q frame, q 's vel = 0
 \Rightarrow no magnetic force

$$\therefore \bar{F} = \bar{F}_E = qE$$

$$F = q \cdot \frac{\lambda_{tot}}{2\pi\epsilon_0 \cdot s}$$

$$= \frac{q}{2\pi\epsilon_0 \cdot s} \cdot \frac{(-2\lambda uv)}{c^2 \sqrt{1 - \frac{u^2}{c^2}}} \quad \dots \quad F \text{ in } q \text{ frame}$$

~~Handwritten scribbles~~

Go back to lab frame:

$$F_{\text{lab}} = \sqrt{1-u^2/c^2} * F_{\text{frame}}$$

$$= \frac{-\lambda v q u}{\pi \epsilon_0 c^2 s}$$

$$c^2 = \frac{1}{\mu_0 \epsilon_0}$$

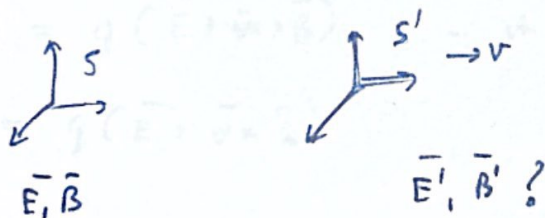
$$= \frac{-q \cdot u \cdot 2\lambda v \cdot \mu_0}{2\pi s}$$

minus sign
 $\equiv \bar{F}$ is opp to \bar{E}
 \equiv up dirn
 $=$ same as before.

$$= \left(\frac{\mu_0 \cdot I}{2\pi s} \right) \cdot q \cdot u$$

\Rightarrow same as our original answer!

Now, let's find the transformation laws for \bar{E} & \bar{B} :



$$\bar{F} = q(\bar{E} + \bar{v} \times \bar{B})$$

$$\bar{F}' = q(\bar{E}' + \bar{v}' \times \bar{B}')$$

\bar{F} & \bar{F}' are connected by transformation laws that we already know.

$$F_x = F'_x$$

$$\gamma = \frac{1}{\sqrt{1-v^2/c^2}}$$

$$F_y = \frac{F'_y}{\gamma}$$

$$F_z = \frac{F'_z}{\gamma}$$

Let $u = v$

$\Rightarrow q$ is in rest ~~at~~ in S'

$$\text{so } \vec{F}'_B = 0$$

& we can focus on \vec{F}'_E

$$\vec{F} = q \vec{E}'$$

$$\vec{F}'_{x,y,z} = q \vec{E}'_{x,y,z} \quad - \text{ in } S'$$

$$\vec{F} = q (\vec{E} + \vec{v} \times \vec{B}) \quad - \text{ in } S$$

$$= q (\vec{E} + \vec{v} \times \vec{B})$$

$$F_x = q (\bar{E}_x + (\vec{v} \times \vec{B})_x)$$

$$F_y = q (\bar{E}_y + (\vec{v} \times \vec{B})_y)$$

$$F_z = q (\bar{E}_z + (\vec{v} \times \vec{B})_z)$$

$$\vec{v} = v \hat{x}$$

* now compare F_x & F'_x

$$q (\bar{E}_x + (\vec{v} \times \vec{B})_x) = q \bar{E}'_x$$

\downarrow
0

$$\text{bec. } \vec{v} = v \hat{x}$$

$$\Rightarrow \boxed{E_x = E'_x}$$

$$F_y = F'_y$$

$$q(\bar{E}_y + (\bar{v} \times \bar{B})_y) = q \bar{E}'_y \cdot \frac{1}{\gamma}$$

$$= q(\bar{E}_y + (v_z \overset{0}{\cancel{B_x}} - B_z v_x) \hat{y}) = q \bar{E}'_y \cdot \frac{1}{\gamma}$$

$$\Rightarrow q \bar{E}_y$$

$$E_y - v_x B_z = \frac{E'_y}{\gamma}$$

$$\Rightarrow \boxed{E'_y = \gamma (E_y - v_x B_z)}$$

similarly:

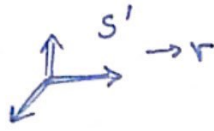
$$\boxed{E'_z = \gamma (E_z + v_x B_y)}$$

Generalising:

$$E_{\parallel}' = E_{\parallel} \quad (\text{parallel to } v_{\text{rel}})$$

$$E_{\perp}' = \gamma [E_{\perp} + (\bar{v} \times \bar{B})_{\perp}]$$

New, kind B transformation:



in S' , q is moving up w.r.t u

Doing some calc & using $\vec{E} - \vec{E}'$ transformations:

$$B_x' = B_x$$

$$B_y' = \gamma \left(B_y + \frac{v}{c^2} E_z \right)$$

$$B_z' = \gamma \left(B_z - \frac{v}{c^2} E_y \right)$$

$$B_{\parallel}' = B_{\parallel}$$

$$B_{\perp}' = \gamma \left(B_{\perp} + \frac{1}{c^2} (\vec{v} \times \vec{E})_{\perp} \right)$$

Special cases:

(i) if $\vec{B} = 0$ in S

$$\vec{B}' = \frac{\gamma v}{c^2} (E_z \hat{y} - E_y \hat{z})$$

but we want to express in terms of E' not E

$$E_z' = \gamma E_z$$

$$E_y' = \gamma E_y$$

$$\Rightarrow \vec{B}' = \frac{v}{c^2} (E_z' \hat{y} - E_y' \hat{z}) = -\frac{1}{c^2} (\vec{v} \times \vec{E}')$$

(ii) if $\vec{E} = 0$ in S

$$\vec{E}' = -\gamma v (B_z \hat{y} - B_y \hat{z})$$

$$= -\gamma v \left(\frac{B_z'}{\gamma} \hat{y} - \frac{B_y'}{\gamma} \hat{z} \right)$$

$$= -v (B_z' \hat{y} - B_y' \hat{z})$$

$$\rightarrow \vec{E}' = \vec{v} \times \vec{B}'$$

Tensors:

$$a'^{\mu} = \Lambda^{\mu}_{\nu} a^{\nu}$$

... an object which obeys this is a four vector

$$F'^{\mu\nu} = \Lambda^{\mu}_{\lambda} \Lambda^{\nu}_{\sigma} F^{\lambda\sigma}$$

... an object which obeys this is a second rank tensor

F will be a 4x4 matrix
= 16 ind. terms

too many? We only need 6 ($E_{x,y,z}$
 $B_{x,y,z}$)

F symm matrix?

- 10 ind. terms \rightarrow still too many

anti-symm?

= 6 ind. terms = just right!

\therefore This will be an antisymmetric second rank tensor. ('This' = The superstructure which manifests as \vec{E} & \vec{B} fields in diff scenarios)

Expanding $F'^{\mu\nu} = \Lambda^{\mu}_{\lambda} \Lambda^{\nu}_{\sigma} F^{\lambda\sigma}$

$$F'^{01} = F^{01}$$

$$F'^{02} = \gamma (F^{02} - \beta F^{12})$$

$$F'^{03} = \gamma (F^{03} + \beta F^{31})$$

$$F'^{23} = F^{23}$$

$$F'^{31} = \gamma (F^{31} + \beta F^{03})$$

$$F'^{12} = \gamma (F^{12} - \beta F^{02})$$

... match these w/ \vec{E} & \vec{B} transformations and construct F

→ Two options:

$$\textcircled{1} \quad F^{01} = \frac{E_x}{c}, \quad F^{02} = \frac{E_y}{c}, \quad F^{03} = \frac{E_z}{c}$$

$$F^{12} = B_z, \quad F^{31} = B_y, \quad F^{23} = B_x$$

$$\textcircled{2} \quad F^{01} = B_x, \quad F^{02} = B_y, \quad F^{03} = B_z$$

$$F^{12} = -\frac{E_z}{c}, \quad F^{31} = -\frac{E_y}{c}, \quad F^{23} = -\frac{E_x}{c}$$

$$\textcircled{1} \rightarrow F^{\mu\nu}$$

$$\textcircled{2} \rightarrow G^{\mu\nu}$$

(the dual)

... to interconvert

$$\frac{\vec{E}}{c} \rightarrow \vec{B}$$

$$\vec{B} \rightarrow -\frac{\vec{E}}{c}$$

$\therefore F^{\mu\nu}$ is

$$\begin{pmatrix} 0 & \frac{E_x}{c} & \frac{E_y}{c} & \frac{E_z}{c} \\ -\frac{E_x}{c} & 0 & B_z & -B_y \\ -\frac{E_y}{c} & -B_z & 0 & -B_x \\ -\frac{E_z}{c} & B_y & B_x & 0 \end{pmatrix}$$

\rightarrow The Electromagnetic Field Tensor

x — x — x
COURSE FIN.

Extra stuff:

• Four current $J^\mu = (c\rho, \vec{J})$

• Continuity eqⁿ: $\frac{\partial J^\mu}{\partial x^\mu} = 0$

• Maxwell's eqn: $\frac{\partial F^{\mu\nu}}{\partial x^\nu} = \mu_0 J^\mu$

$$\frac{\partial G^{\mu\nu}}{\partial x^\nu} = 0$$

• Lorentz Force Law :

$$F^\mu = q v_\nu F^{\mu\nu}$$

• Magnetic vector potential :

$$A^\mu = \left(\frac{v}{c}, \bar{A} \right) ; v = \text{scalar pot. of } \bar{E}$$

• $F^{\mu\nu} = \frac{\partial A^\nu}{\partial x^\mu} - \frac{\partial A^\mu}{\partial x^\nu}$

• $\square^2 A^\mu = -\mu_0 J^\mu$

$$\square^2 = \frac{\partial}{\partial x^\nu} \frac{\partial}{\partial x^\mu} \equiv \nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}$$

↓
The D'Alembertian

* Norm of a tensor : (Learn this for exam)

$$F^{MV} F_{MV}$$

* to flip an index on top

(it should have at least one zero)

(flip it & put one minus per zero)

* if no zero, you

flip it w/o
sign change

$$= F^{00} F_{00} = F^{00} F^{00}$$

$$+ F^{01} F_{01} = -F^{01} F^{01}$$

$$+ F^{12} F_{12} = F^{12} F^{12}$$

& so on.

The end.